

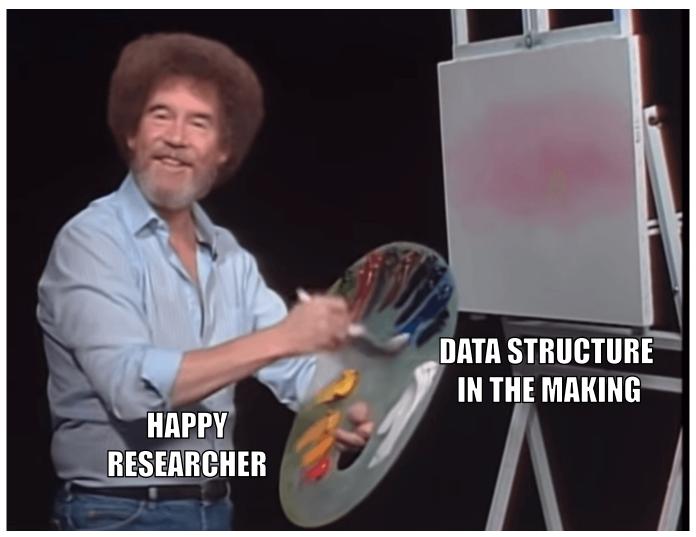
XIndex: A Scalable Learned Index for Multicore Data Storage

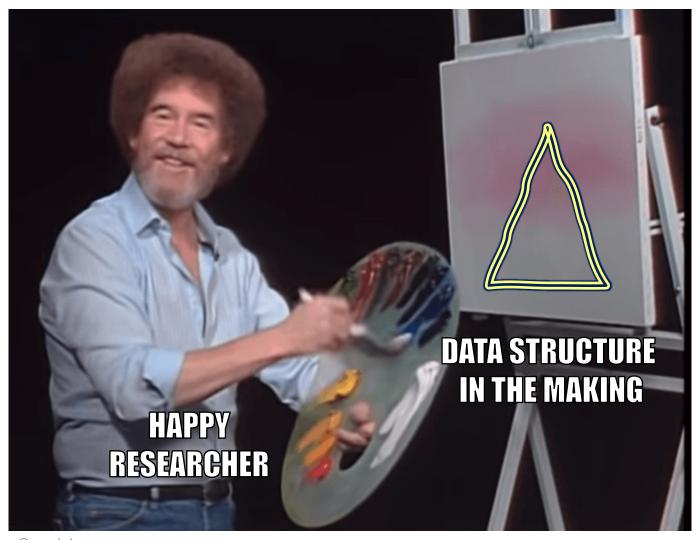
Chuzhe Tang, Youyun Wang, Zhiyuan Dong, Gansen Hu Zhaoguo Wang, Minjie Wang, Haibo Chen



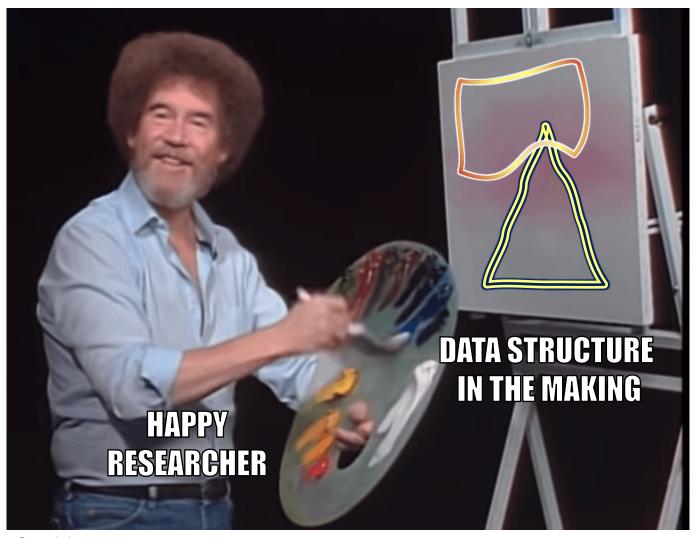




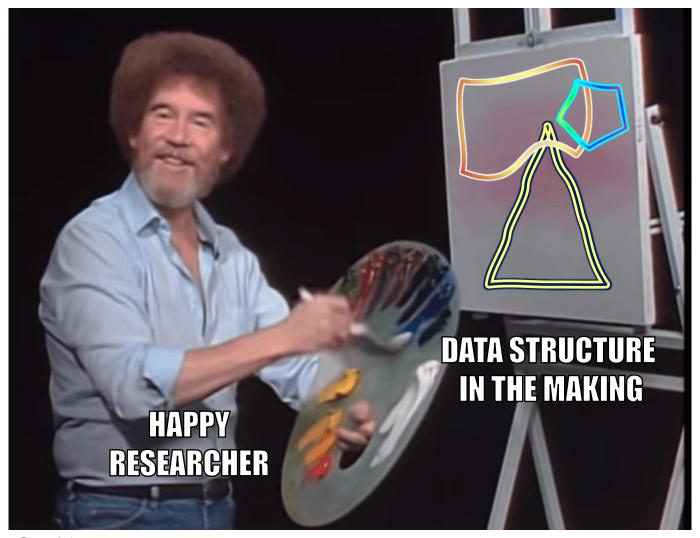




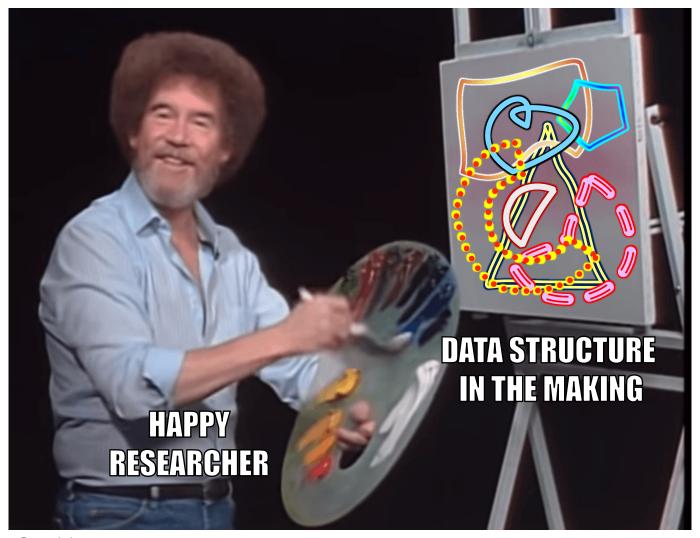
"Gotta have some low latency."



"Gotta have some scalability."

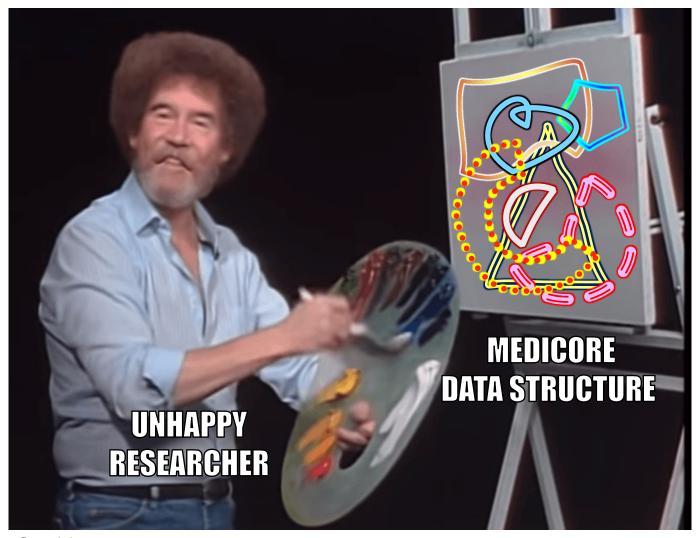


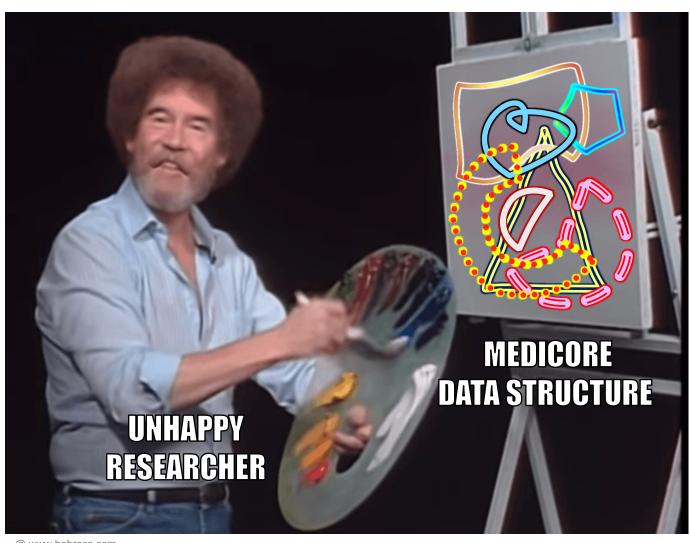
"Gotta have some consistency."

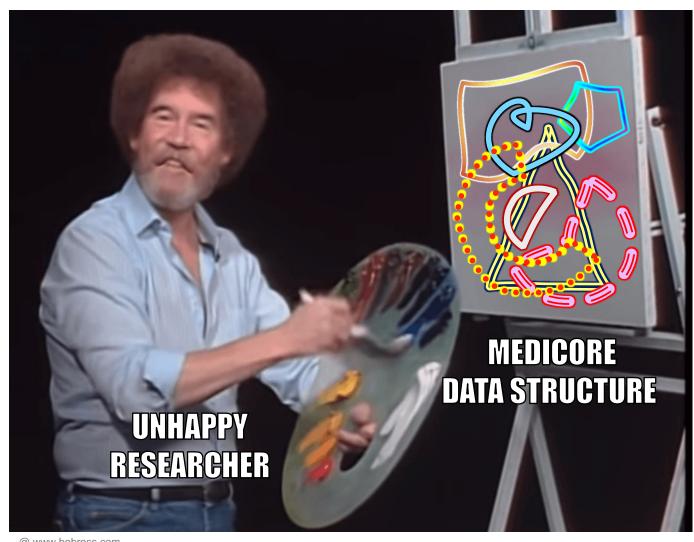


@ www.bobross.com

"Gotta have some small memory footprint, durability, adaptiveness, ..."



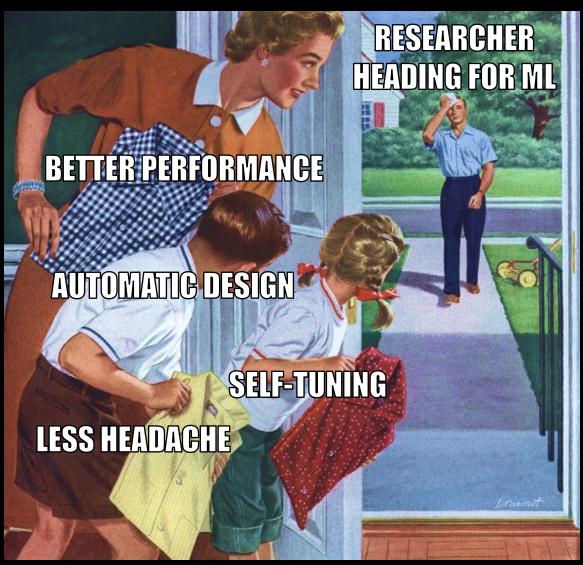




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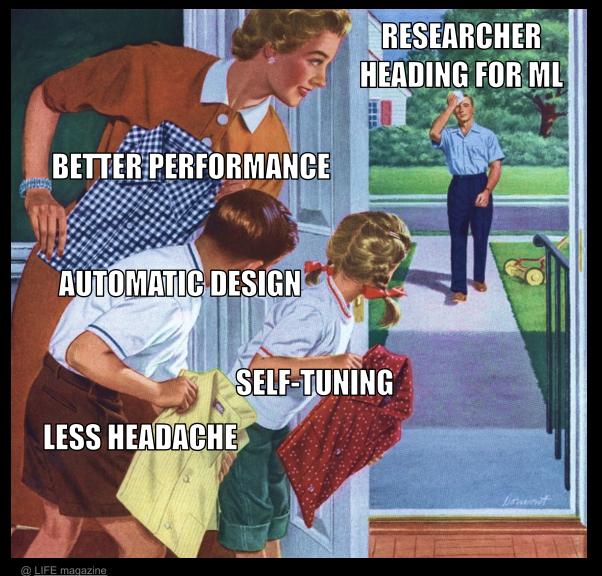
Let's do some Machine Learning!

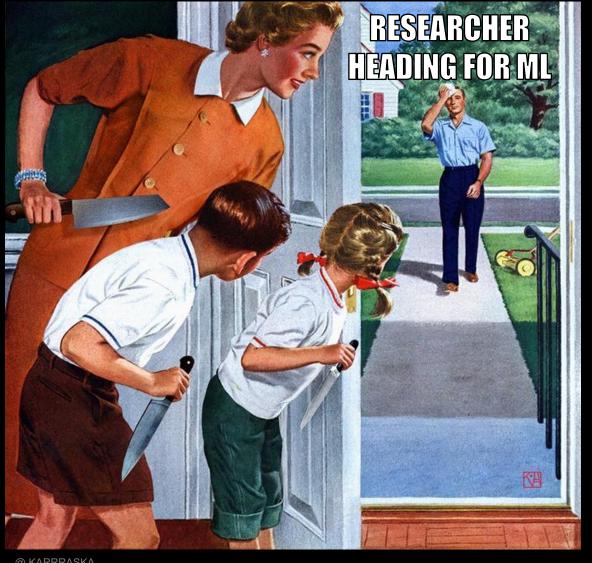




@ LIFE magazine

Expectation

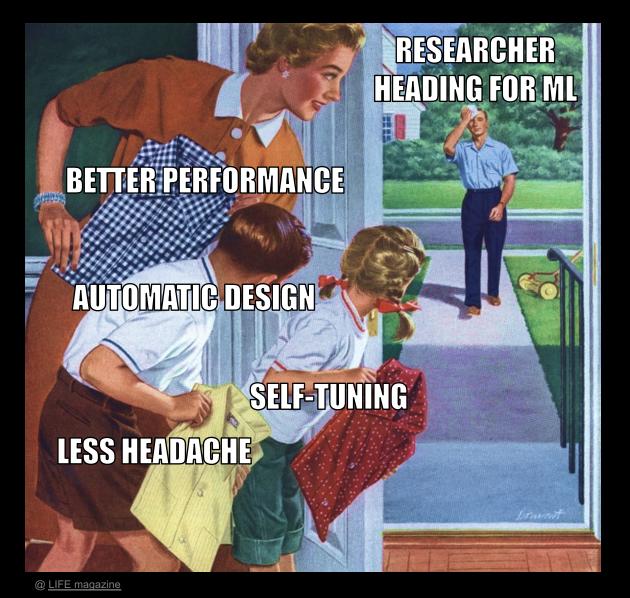


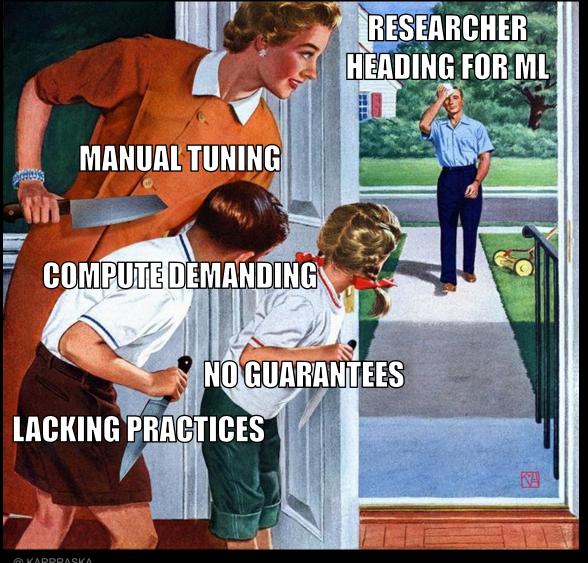


@ KARRRASKA

Expectation

Reality





Expectation

@ KARRRASKA

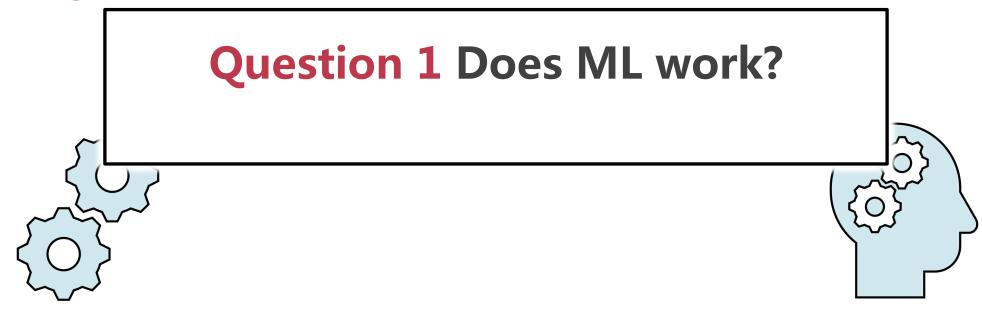
Reality



Data Structure Design

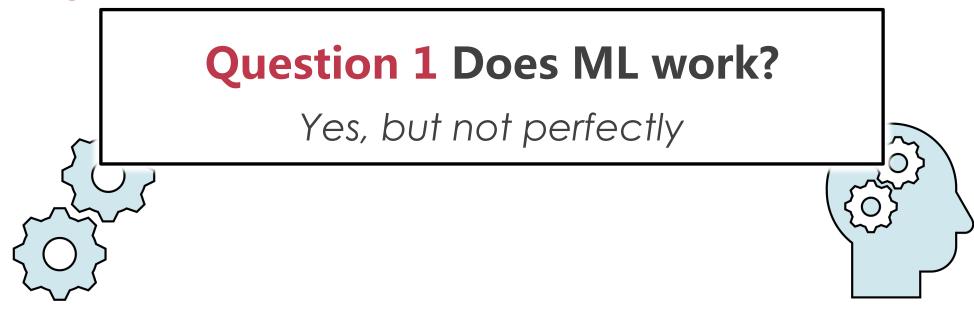


Machine Learning



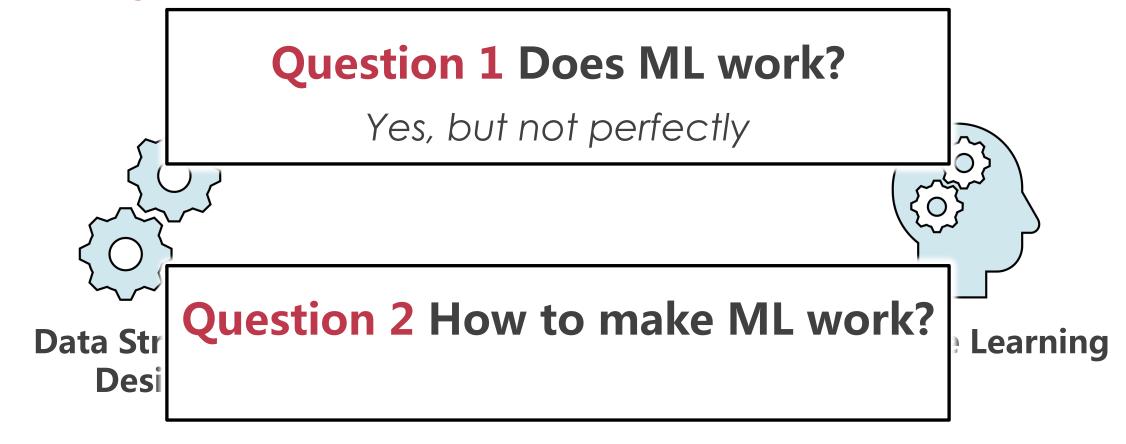
Data Structure Design

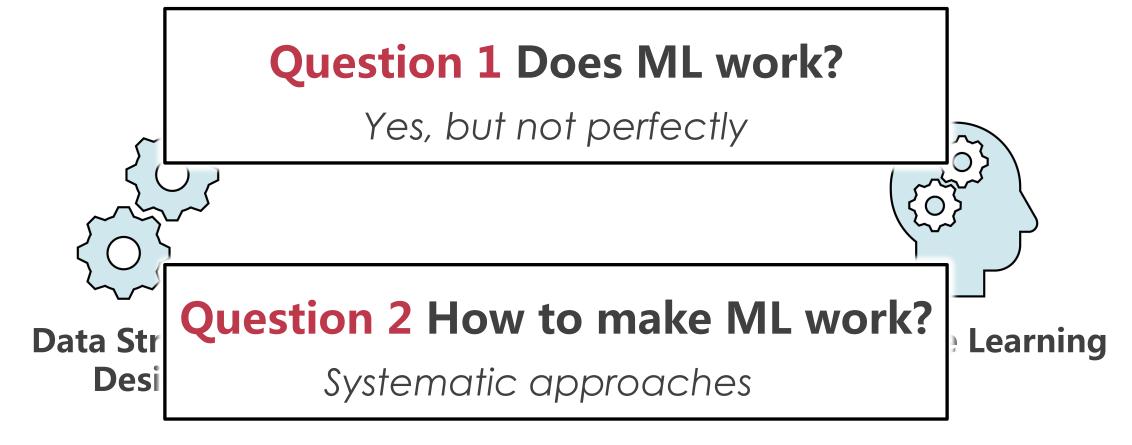
Machine Learning

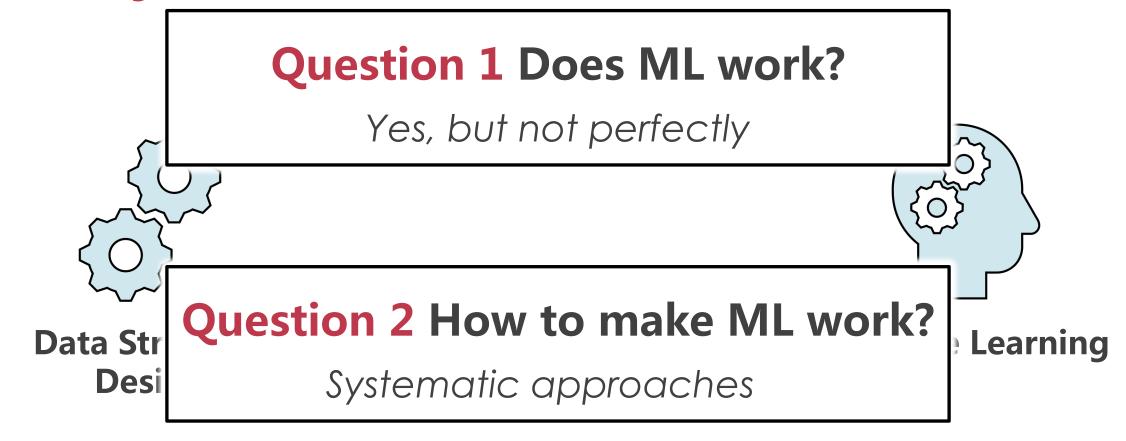


Data Structure Design

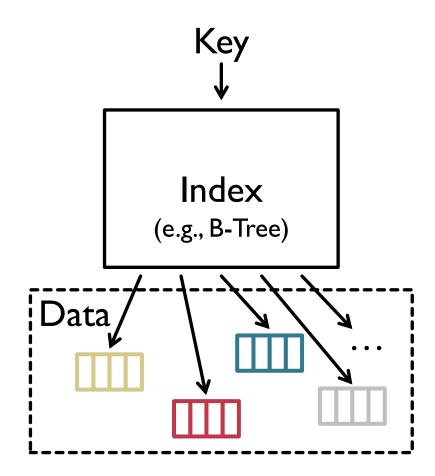
Machine Learning

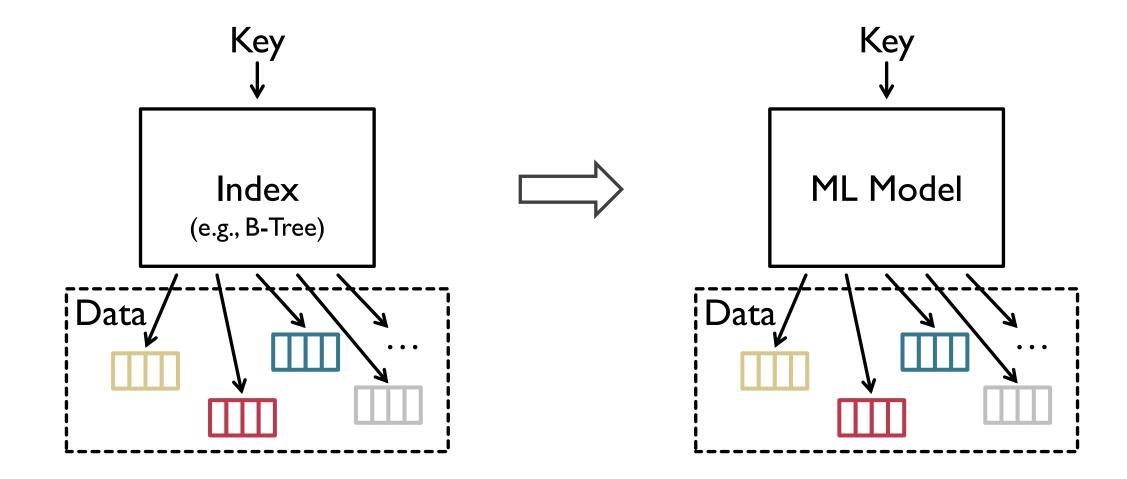


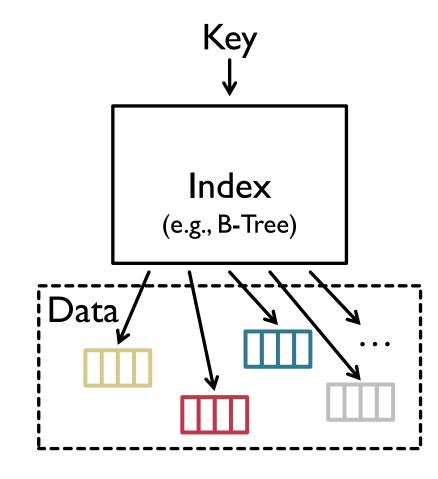


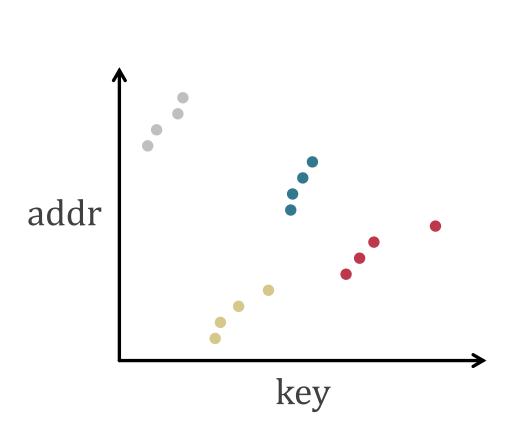


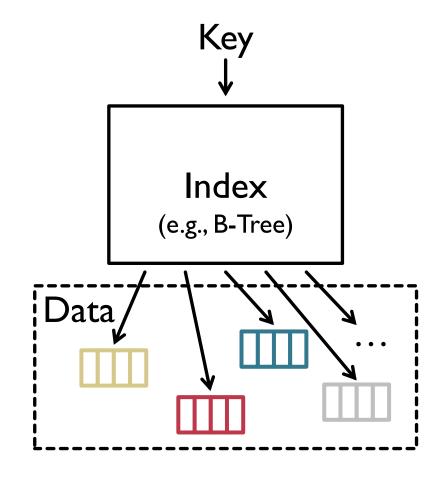
We answer with the learned index



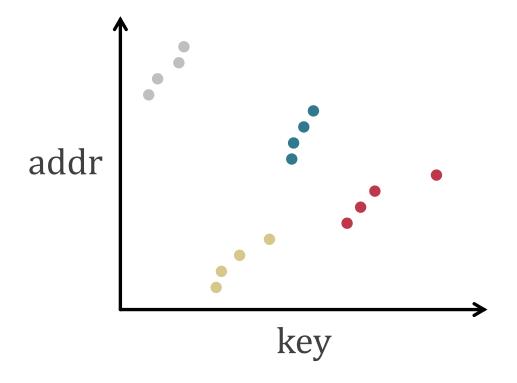


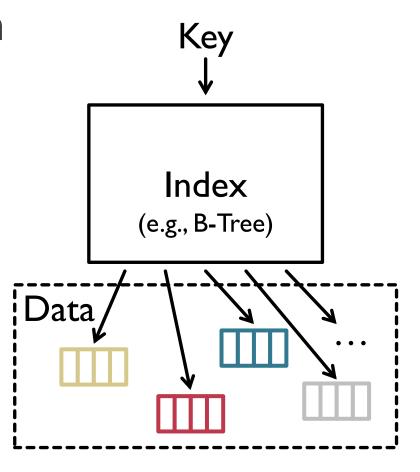




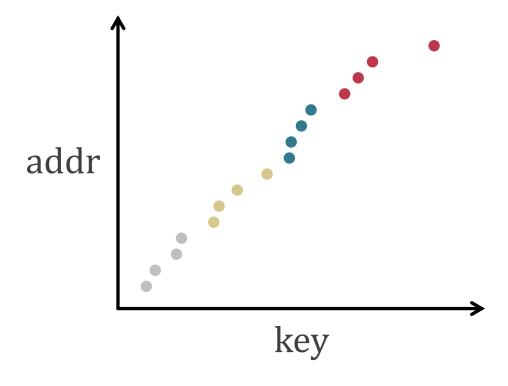


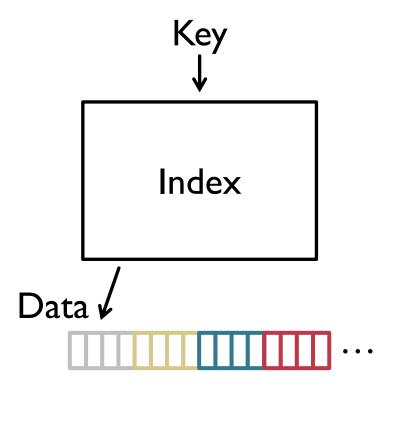
With contiguously sorted data



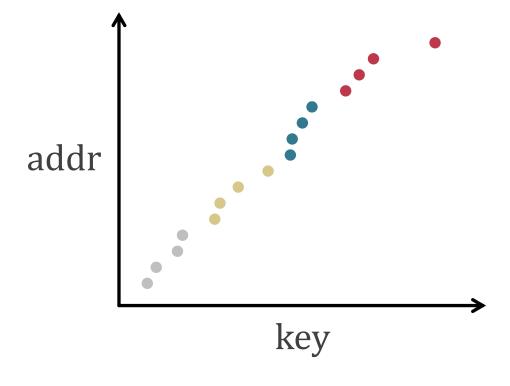


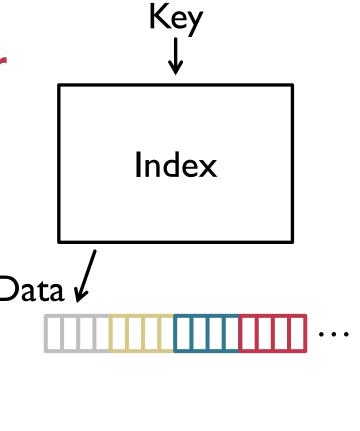
With contiguously sorted data





 With contiguously sorted data, index functions become simpler

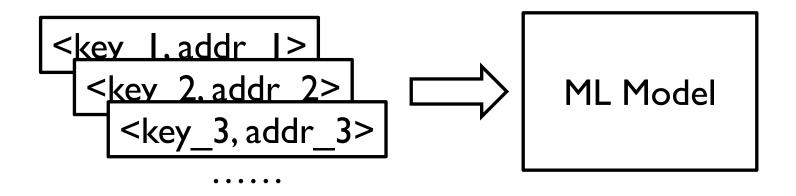




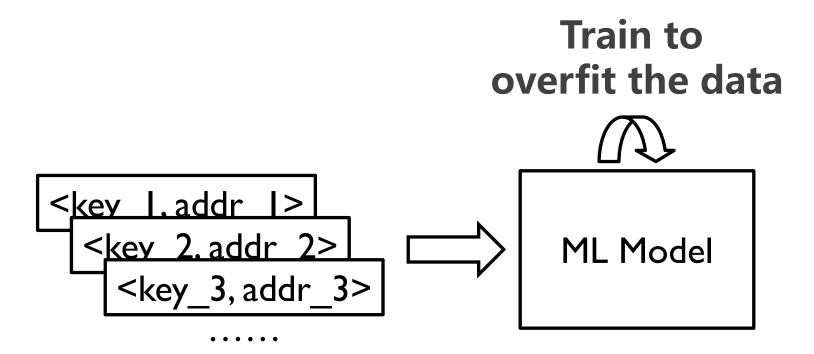
1. Sort data, train model with key-address mapping

ML Model

1. Sort data, train model with key-address mapping



1. Sort data, train model with key-address mapping



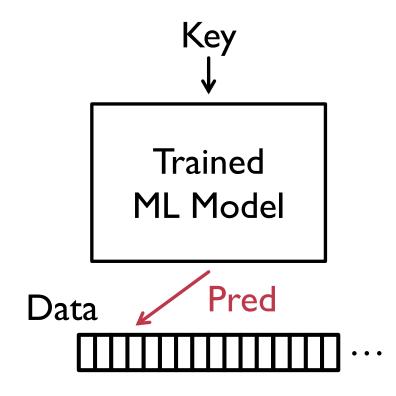
- 1. Sort data, train model with key-address mapping
- 2. Predict addresses with the trained model



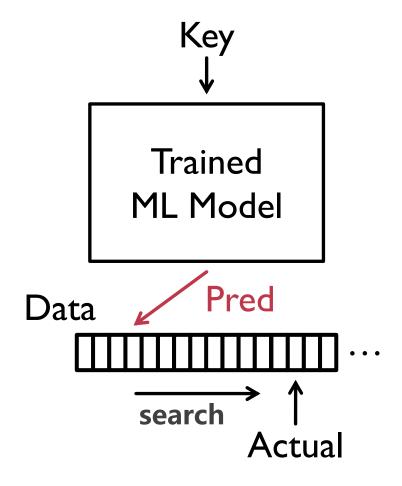
- 1. Sort data, train model with key-address mapping
- 2. Predict addresses with the trained model
 - Prediction is CLOSE, but NOT PRECISE



3. Search the correct position

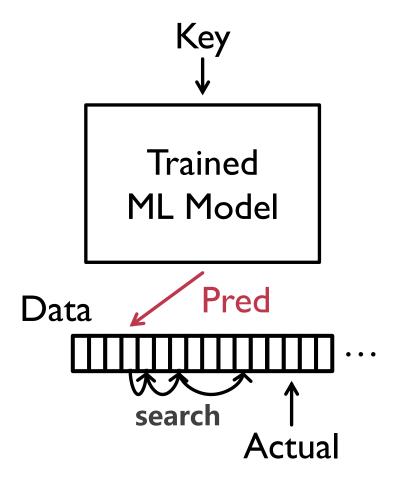


3. Search the correct position



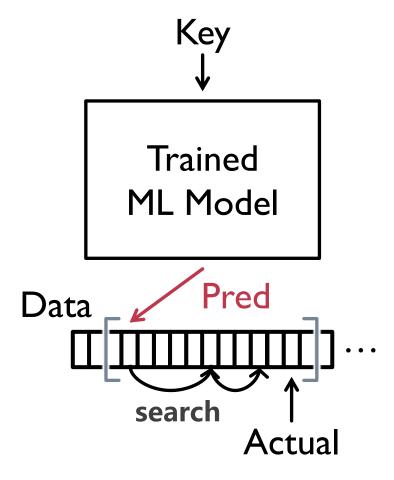
3. Search the correct position

Exponential search



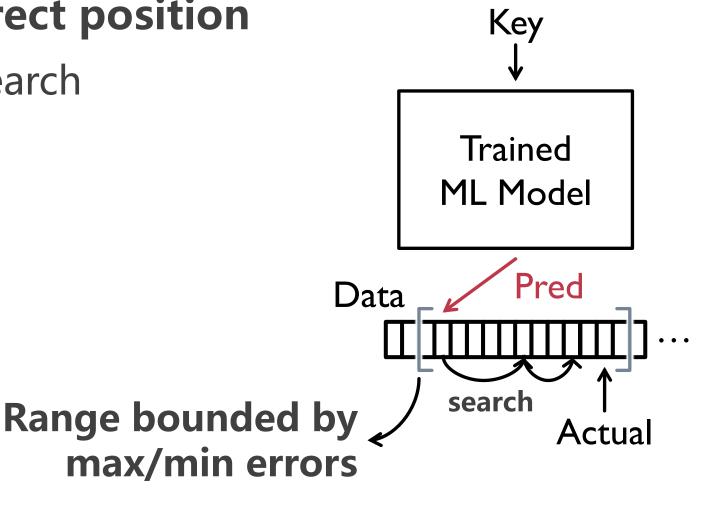
3. Search the correct position

- Exponential search
- Binary search



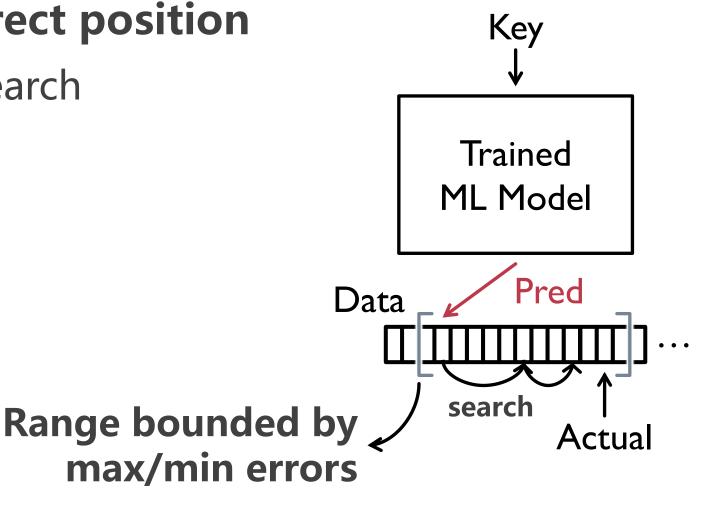
3. Search the correct position

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3. Search the correct position

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- _



3. Search the correct position

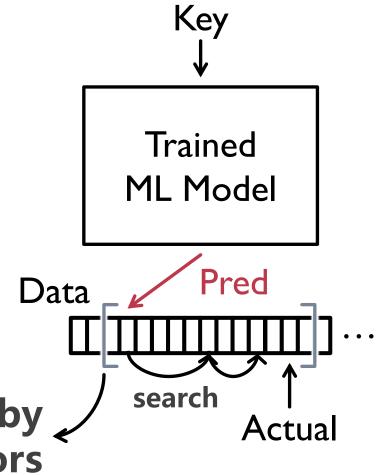
Exponential search

Pinary coarch

Smaller errors

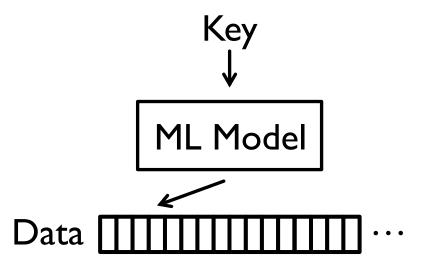


Better search efficiency

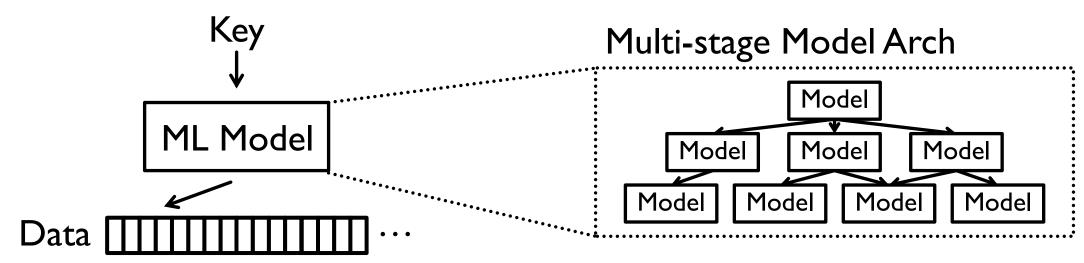


Range bounded by max/min errors

Multi-stage models learn indexes efficiently

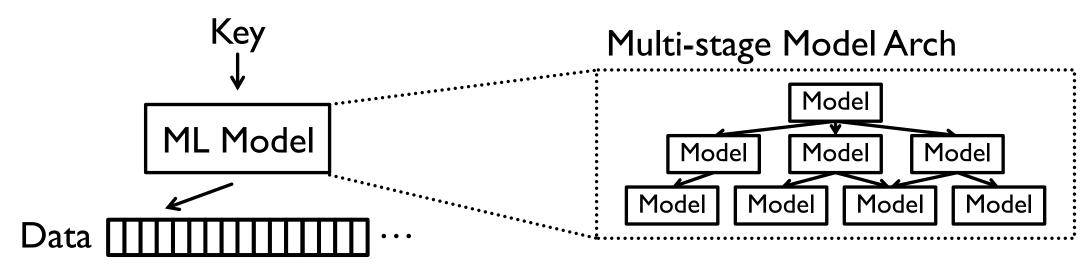


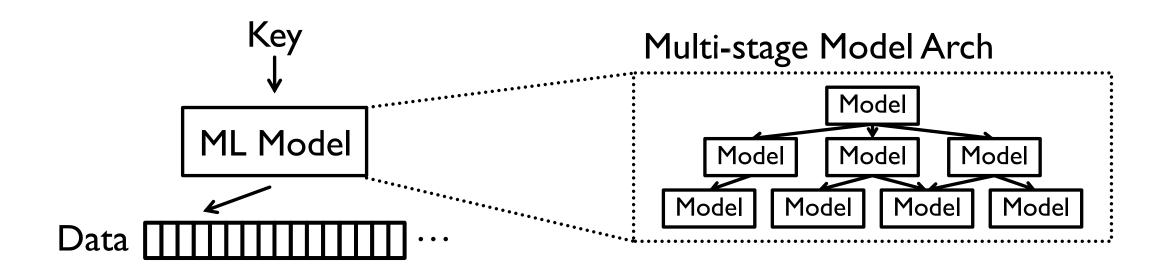
Multi-stage models learn indexes efficiently



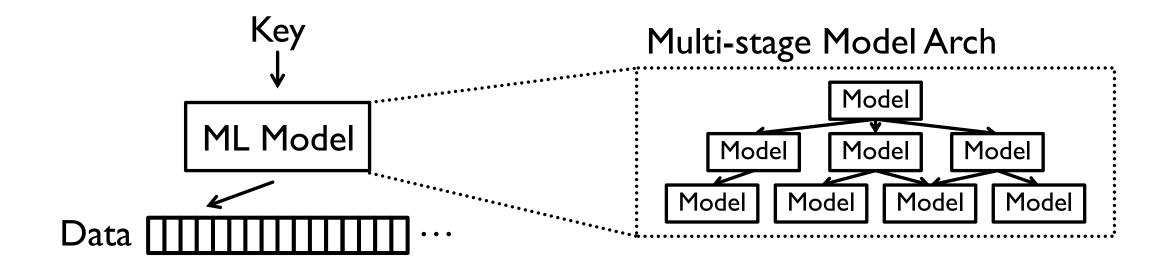
Multi-stage models learn indexes efficiently

Reduce 63% read latency and 99% memory usage

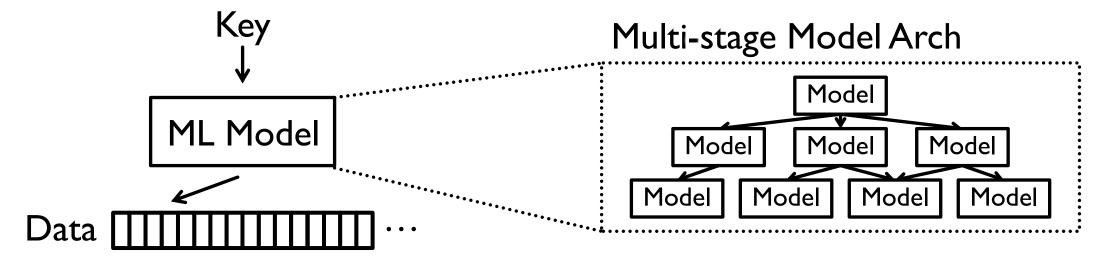




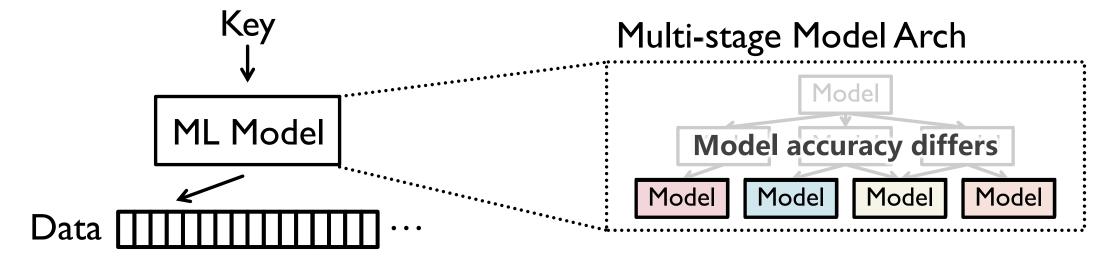
- ISSUE 1 read-only, and non-trivial to support writes
 - Takes several seconds to sort millions of records



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- ISSUE 2 performance degrades in certain workloads
 - 23% worse than B-Tree in a specific access pattern



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How to efficiently support writes and concurrency?

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SOLUTION: buffer inserts and compact periodically

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SOLUTION: adjust the structure at runtime **HEURISTICS** for small model errors and buffer sizes

How to efficiently support writes and concurrency?

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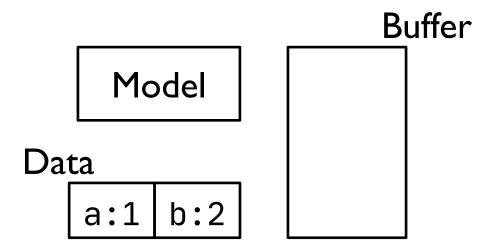
Up to 4.4× better perf than the state-of-the-arts

Model

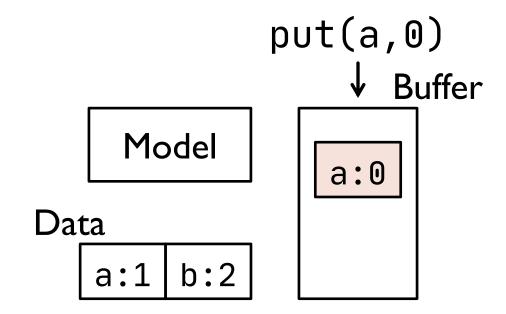
Data

a:1 b:2

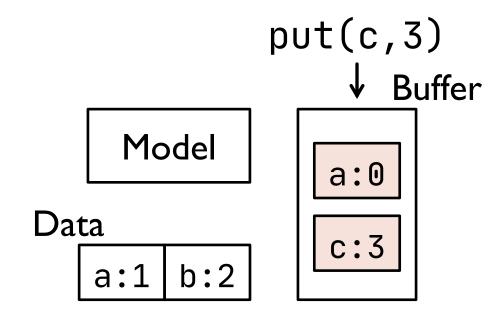
1. Buffers all writes separately (e.g., in a B-Tree)



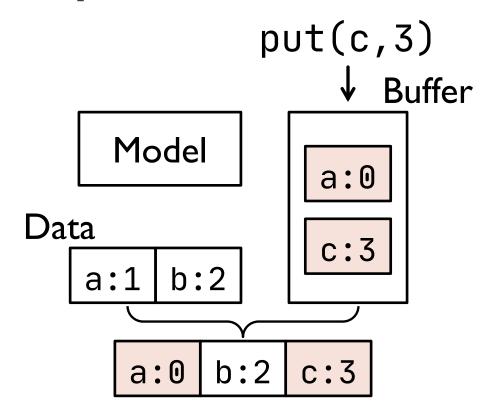
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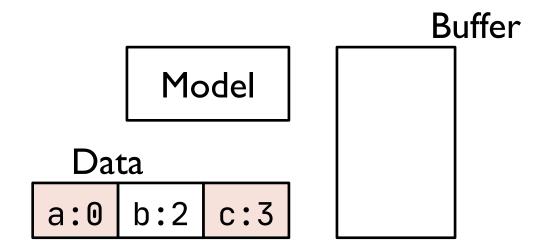
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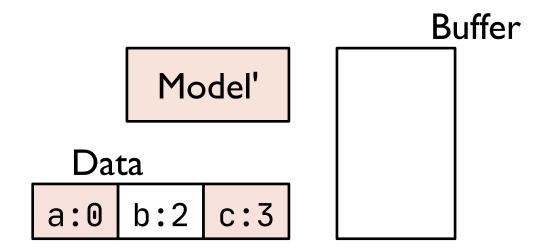
- 1. Buffers all writes separately (e.g., in a B-Tree)
- 2. Periodically compact the buffer

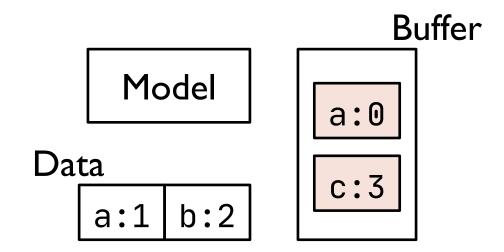


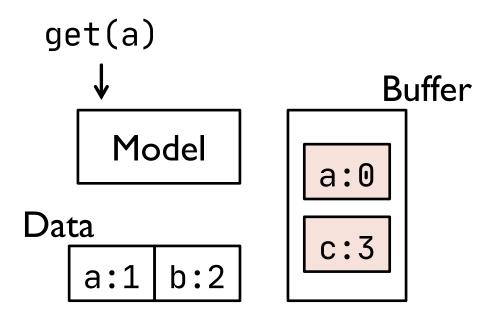
- 1. Buffers all writes separately (e.g., in a B-Tree)
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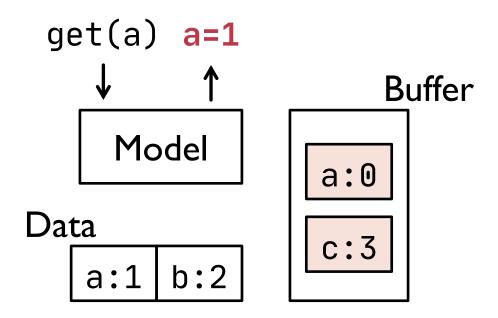


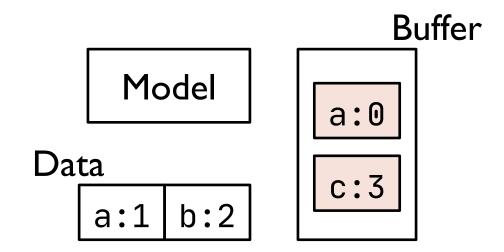
- 1. Buffers all writes separately (e.g., in a B-Tree)
- 2. Periodically compact the buffer and retrain the model

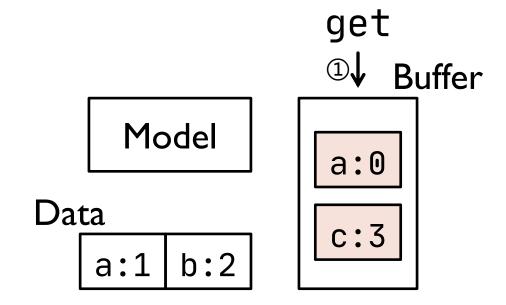


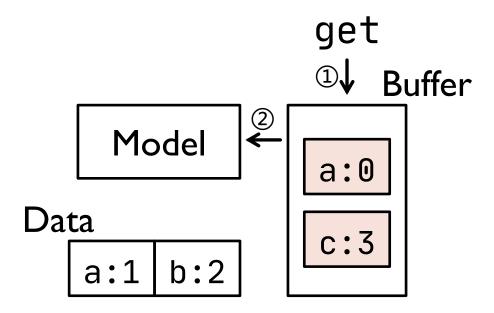




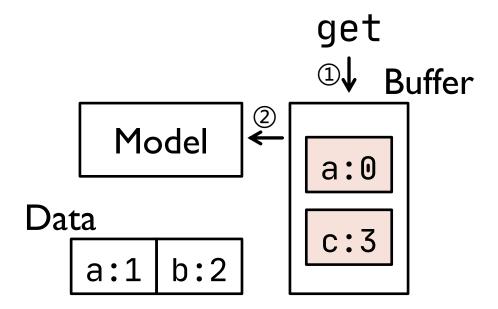




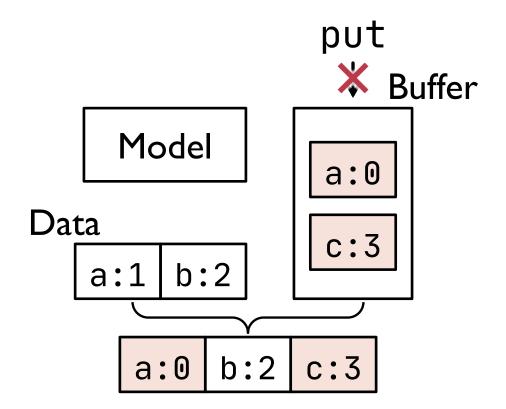




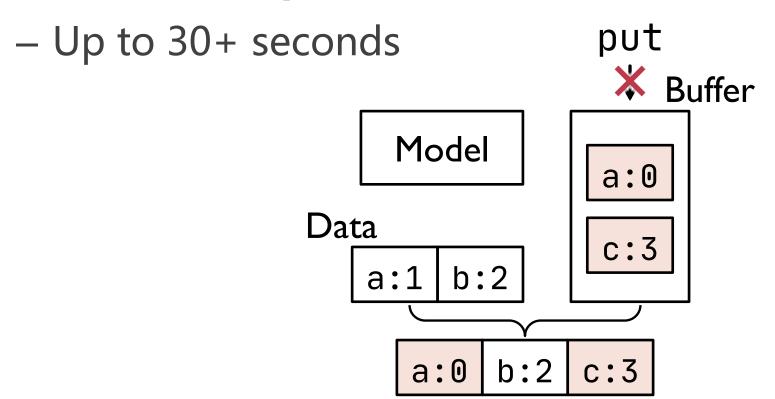
- ISSUE 1: Reads get slower, due to buffer lookup
 - More than 100% slow down



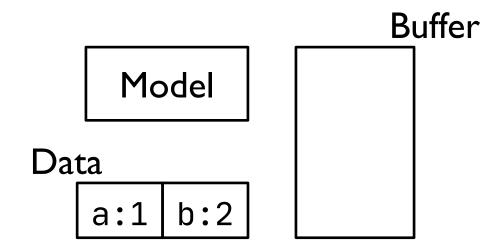
- ISSUE 1: Reads get slower, due to buffer lookup
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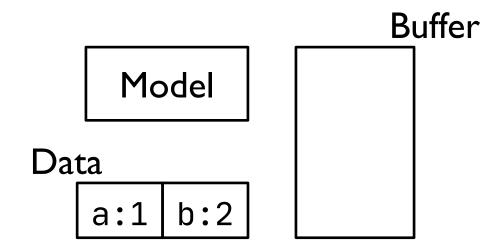
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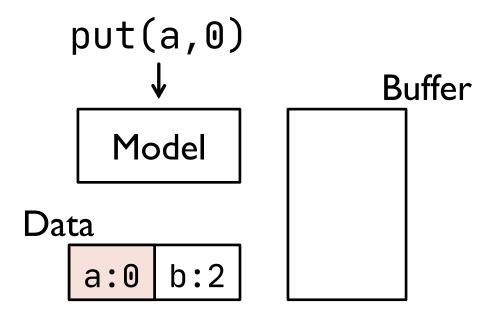
1. Avoid buffer lookups for reads



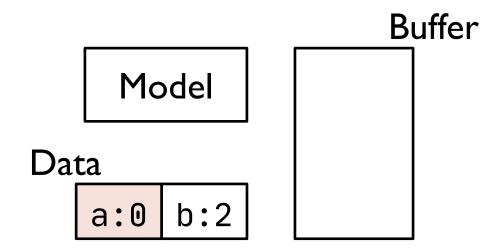
1. Avoid buffer lookups for reads



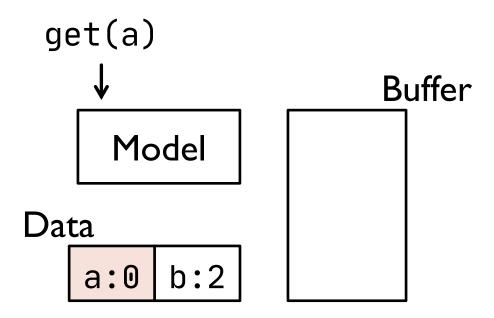
1. Avoid buffer lookups for reads



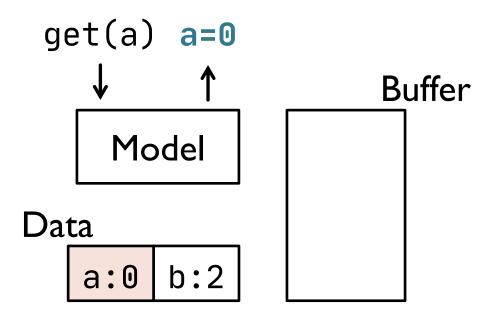
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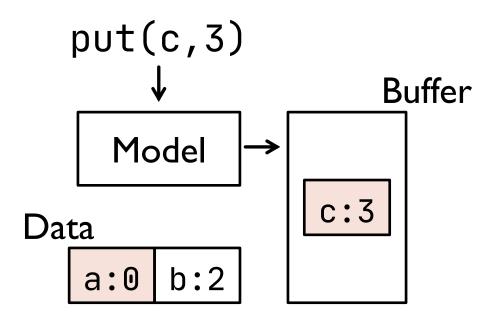
1. Avoid buffer lookups for reads



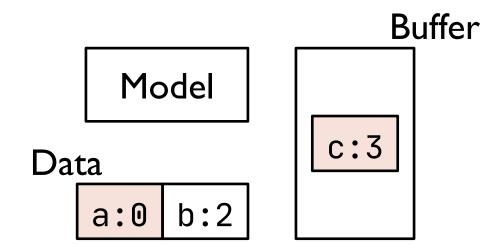
1. Avoid buffer lookups for reads

By performing updates in-place, and buffering only

insertions

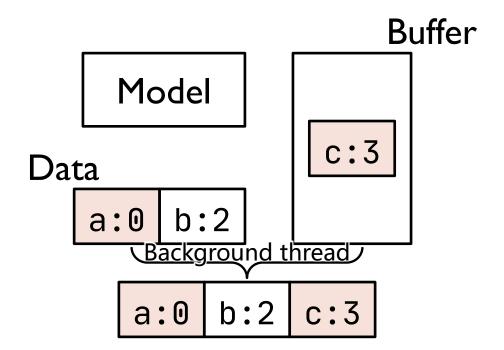


2. Avoid blocking writes



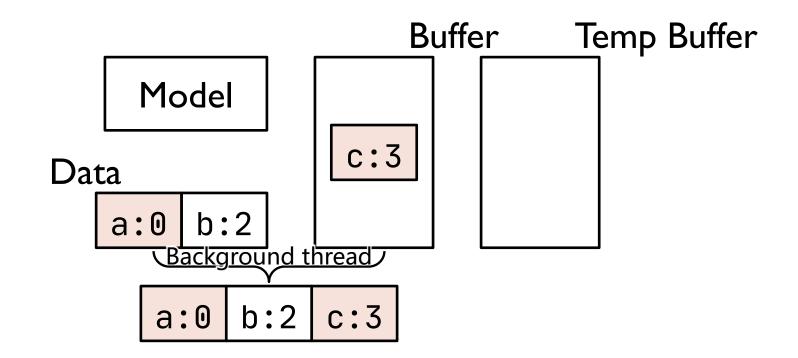
2. Avoid blocking writes

By compacting asynchronously



2. Avoid blocking writes

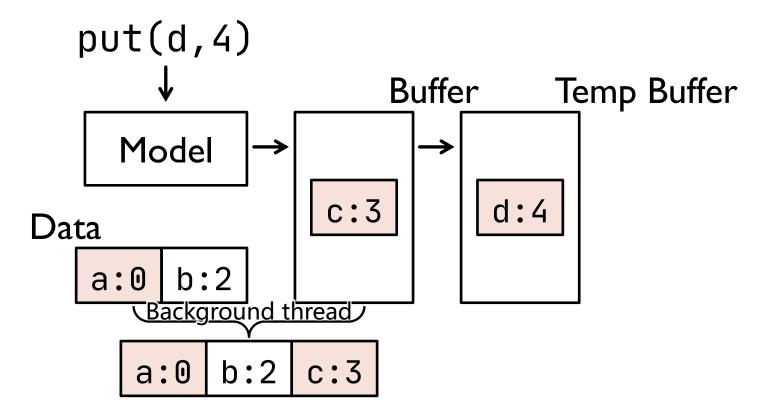
By compacting asynchronously, and using a temporary buffer



2. Avoid blocking writes

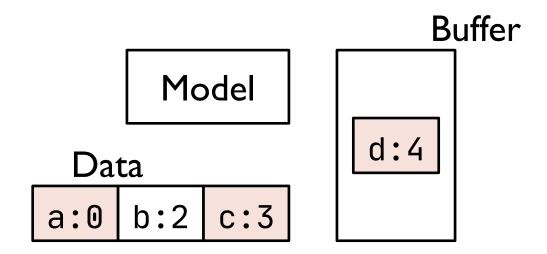
By compacting asynchronously, and using a temporary

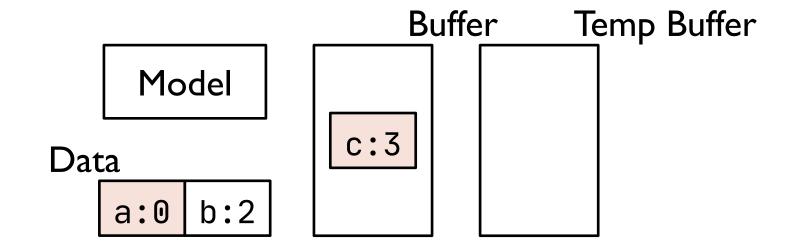
buffer

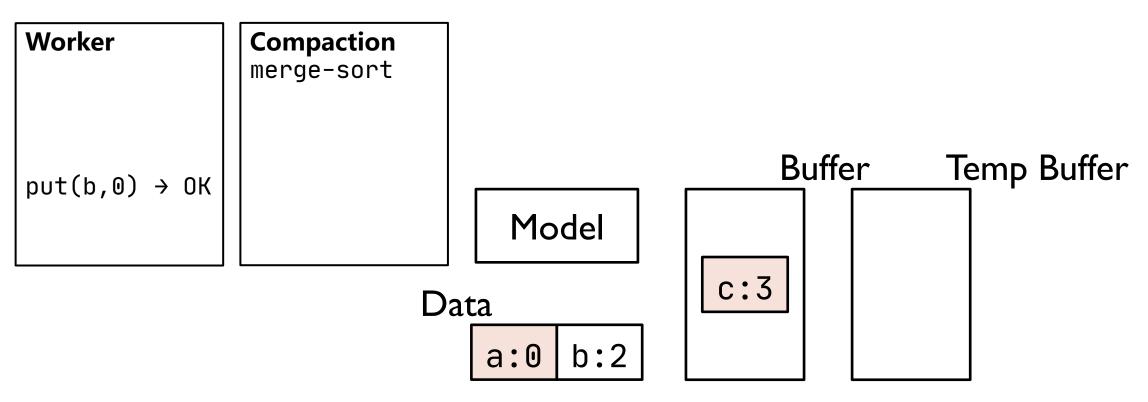


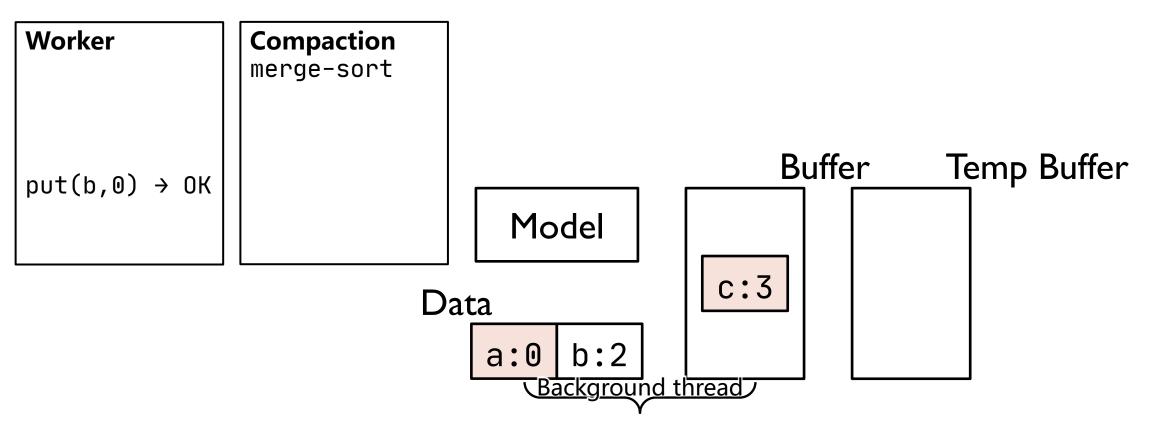
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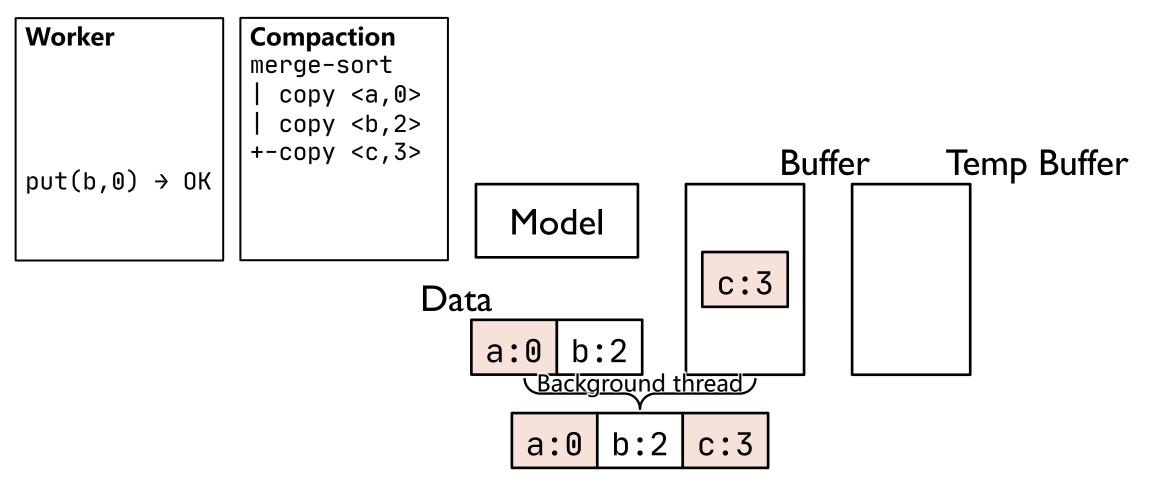
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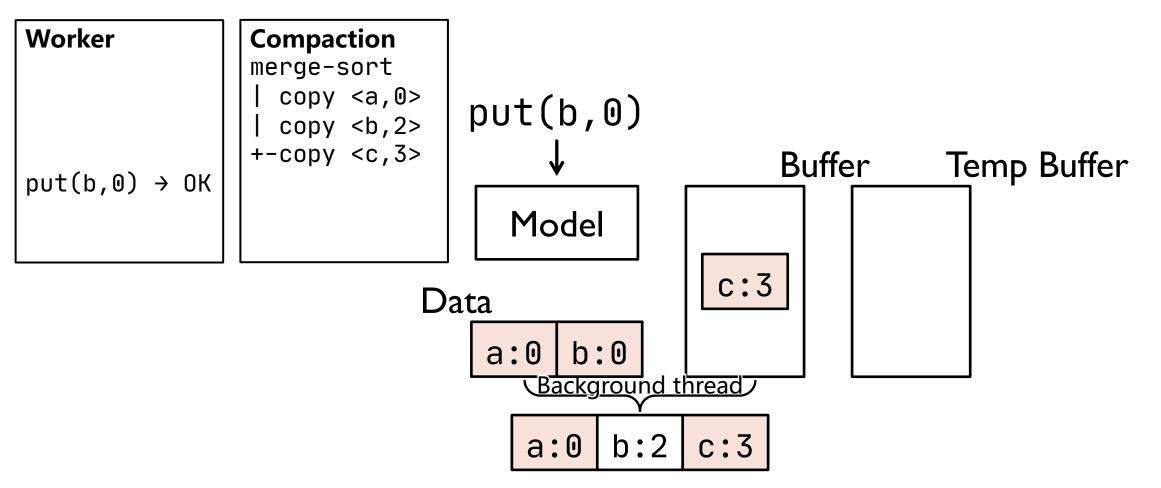


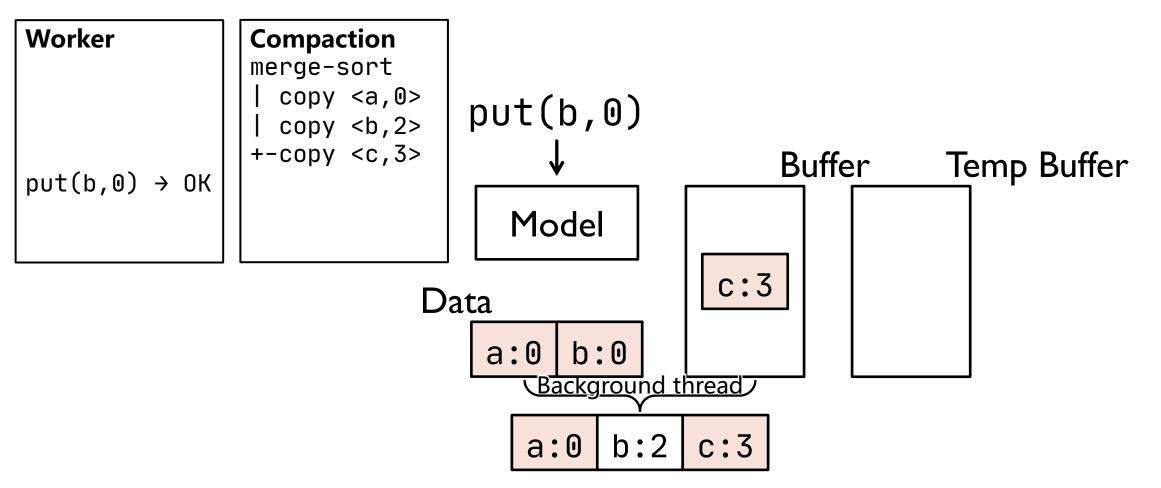












CONSISTENCY ISSUE: Updates are lost!

Worker

 $put(b,0) \rightarrow 0K$

Compaction

merge-sort copy <a,0> copy <b,2> +-copy <c,3>

update array

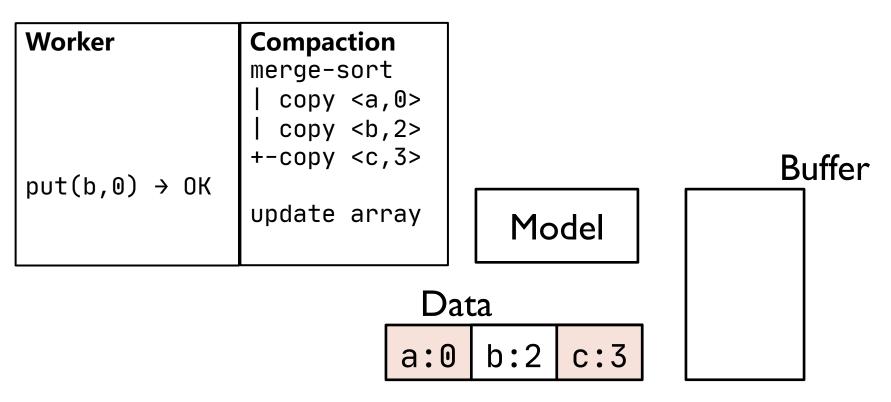
Buffer

Model

Data

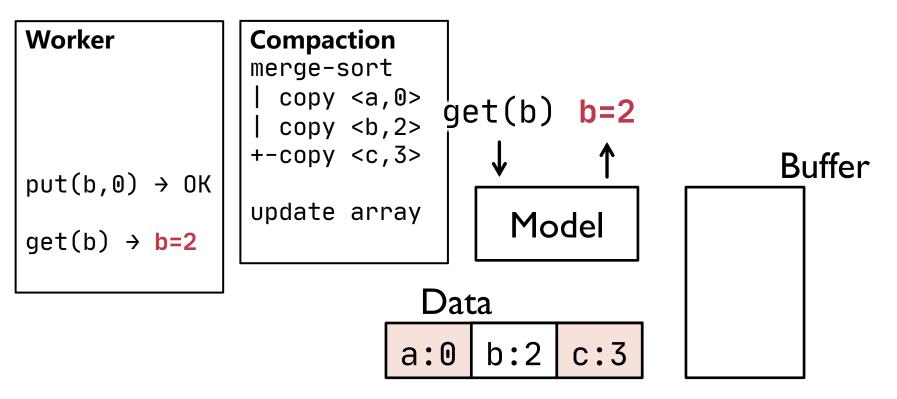
b:2 a:0 c:3

CONSISTENCY ISSUE: Updates are lost!



keeps stale value (b=2)

CONSISTENCY ISSUE: Updates are lost!



keeps stale value (b=2)

How to efficiently and correctly handle writes?

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Cannot slow down reads

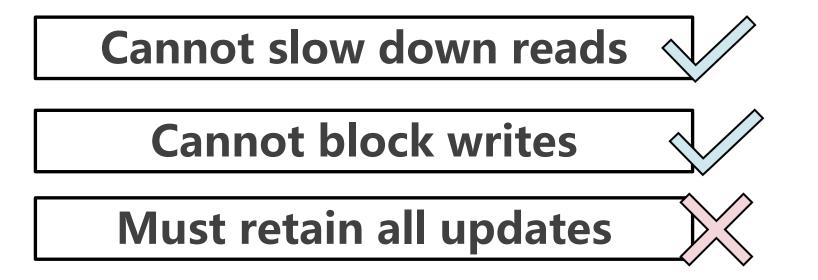


How to efficiently and correctly handle writes?

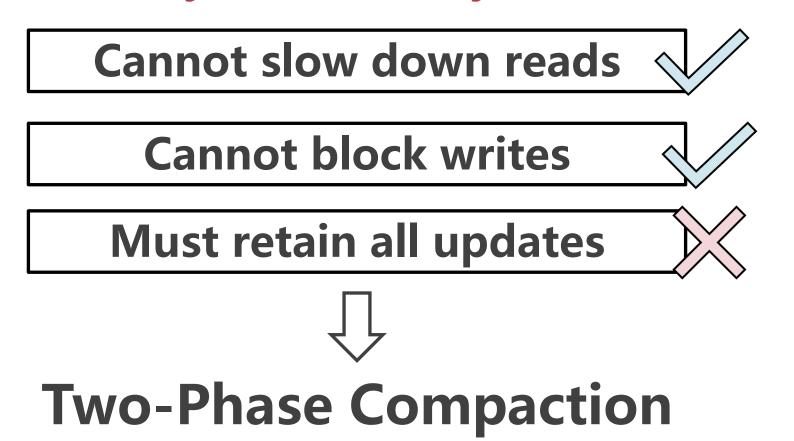
Cannot slow down reads

Cannot block writes

How to efficiently and correctly handle writes?



How to efficiently and correctly handle writes?



OBSERVATION: duplicate records cause inconsistency

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IDEA: not to create duplicates during compaction

OBSERVATION: duplicate records cause inconsistency

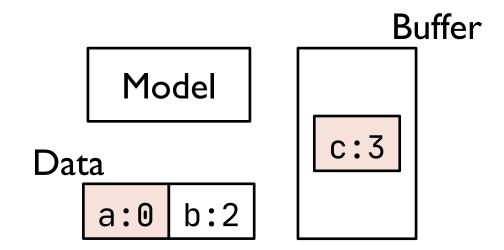
IDEA: not to create duplicates during compaction

METHOD: 2-Phase Compaction — merge, then copy

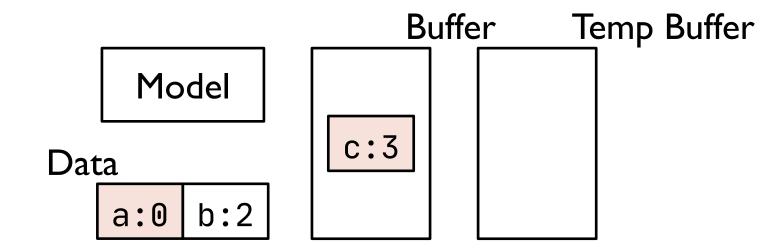
OBSERVATION: duplicate records cause inconsistency

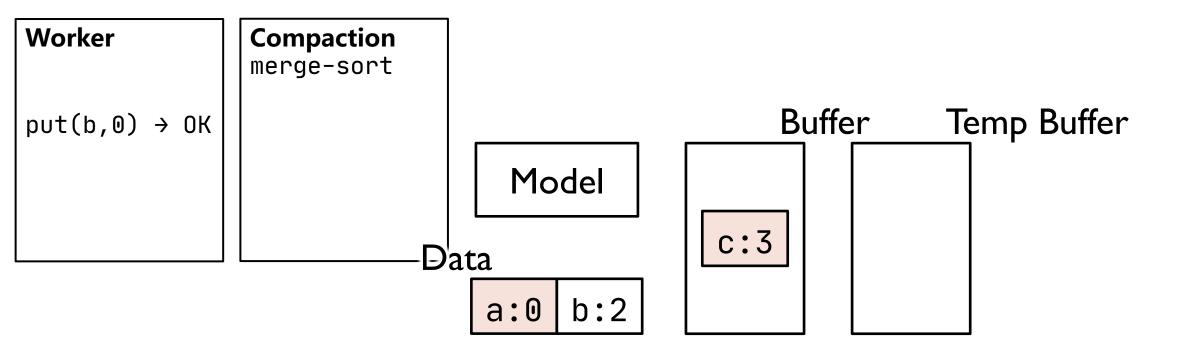
IDEA: not to create duplicates during compaction

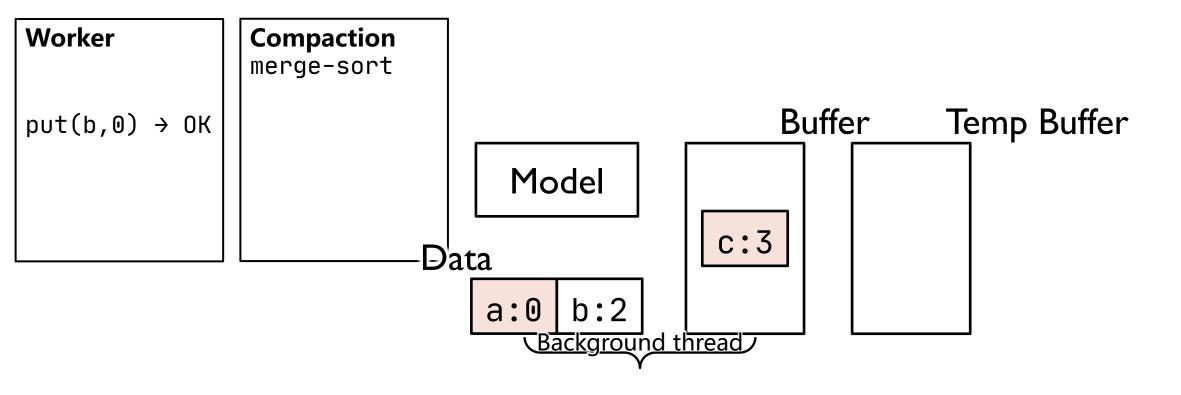
- METHOD: 2-Phase Compaction merge, then copy
 - Still update in-place and compact asynchronously

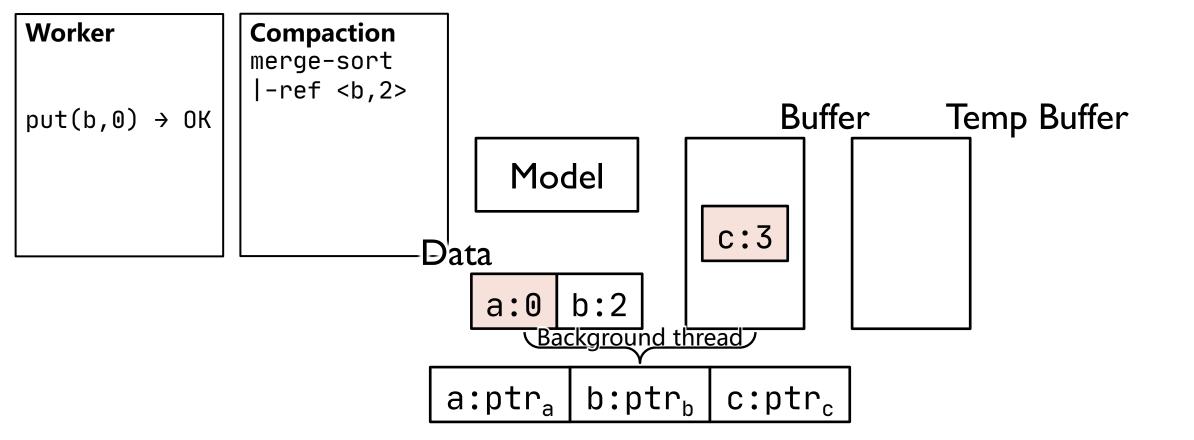


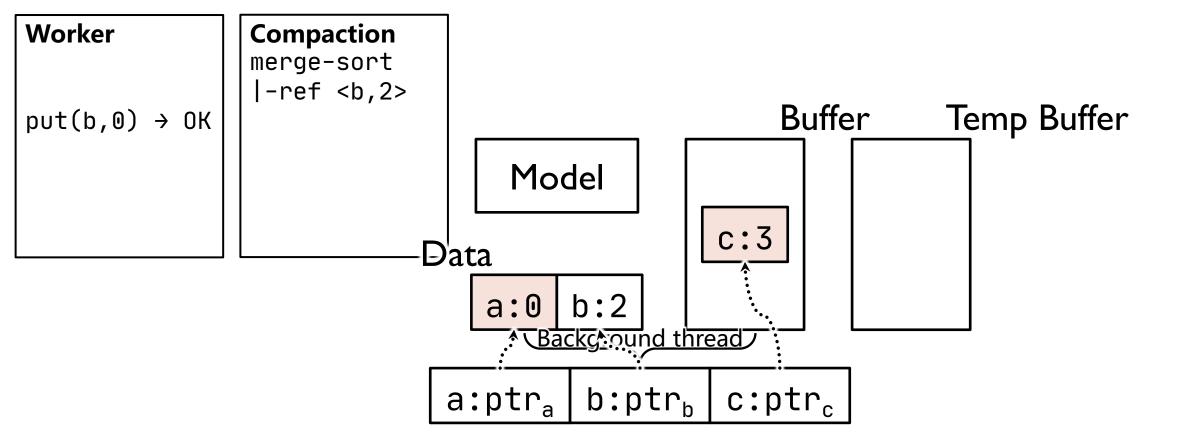
1. MERGE PHASE: merge-sort records on pointers

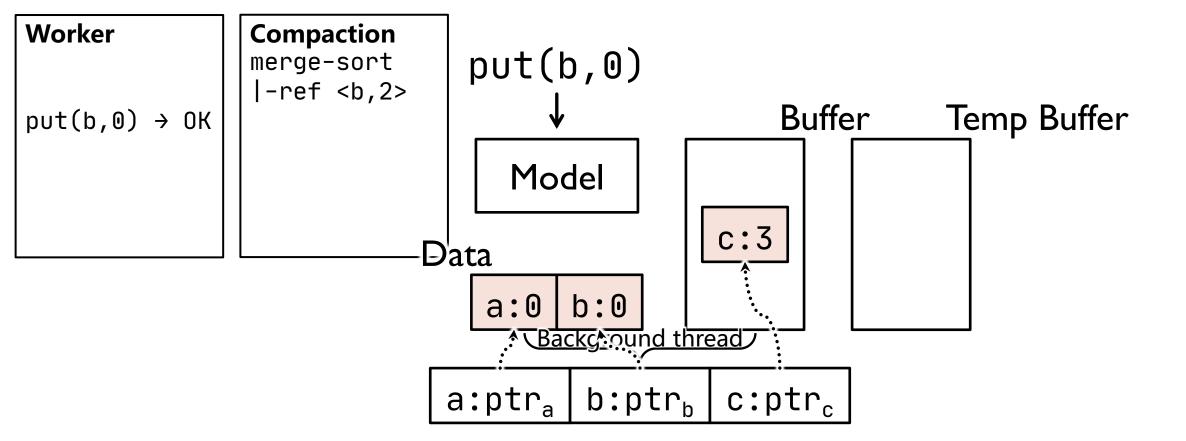




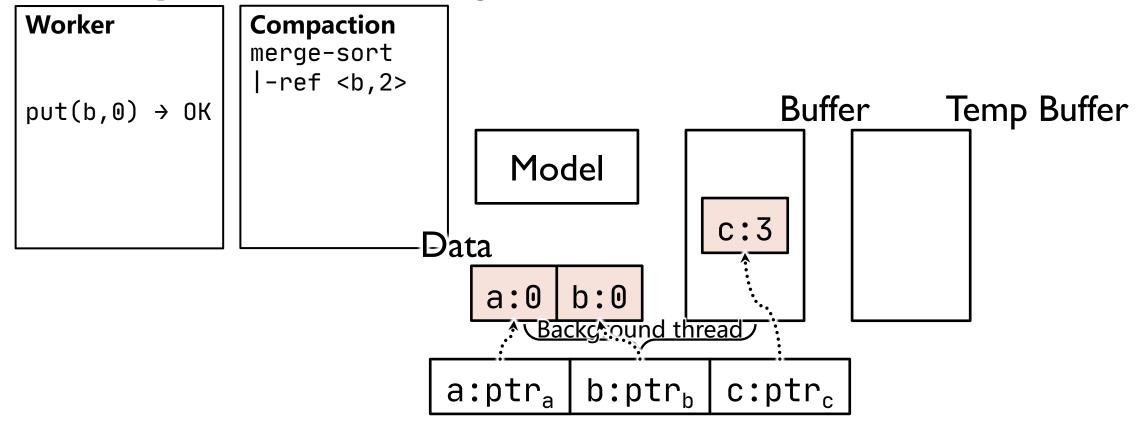




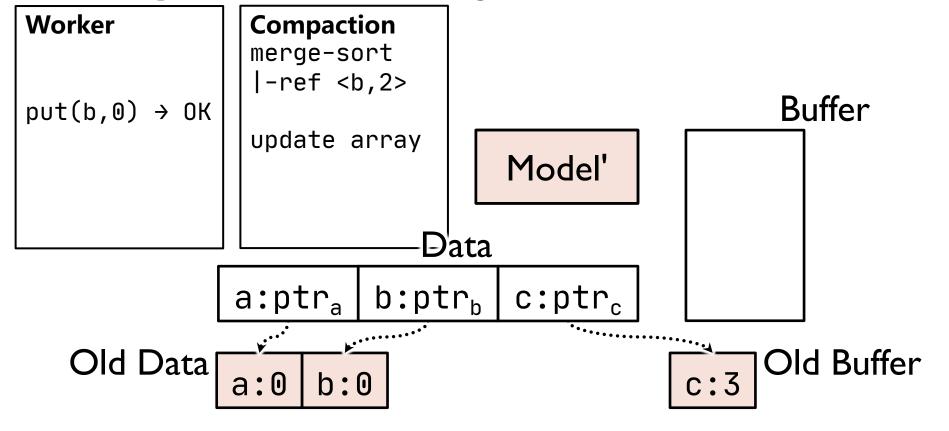




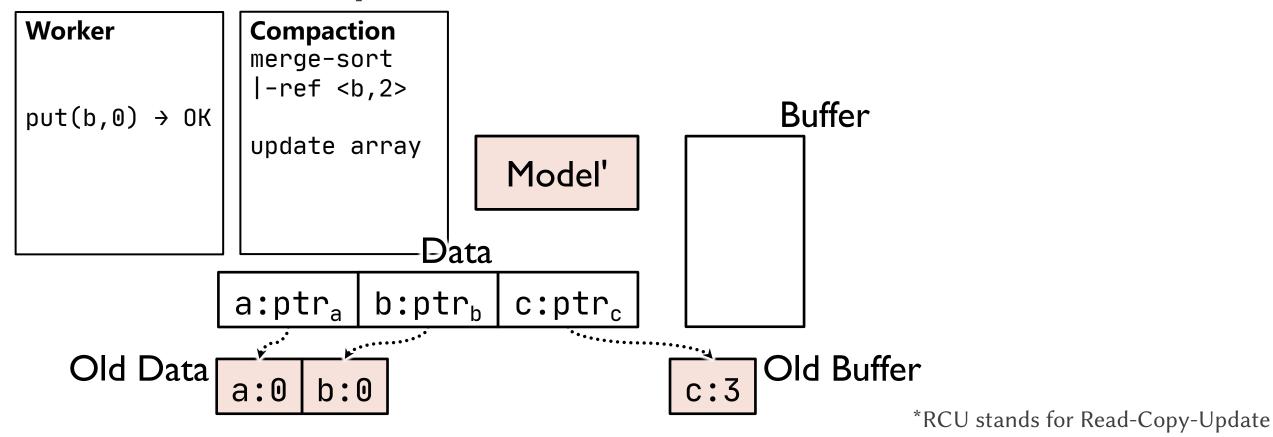
1. MERGE PHASE: merge-sort records on pointers, update data array, and retrain model



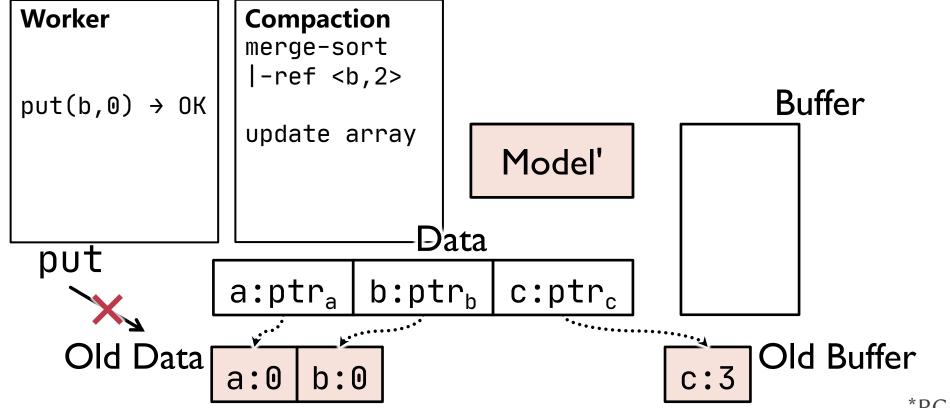
1. MERGE PHASE: merge-sort records on pointers, update data array, and retrain model



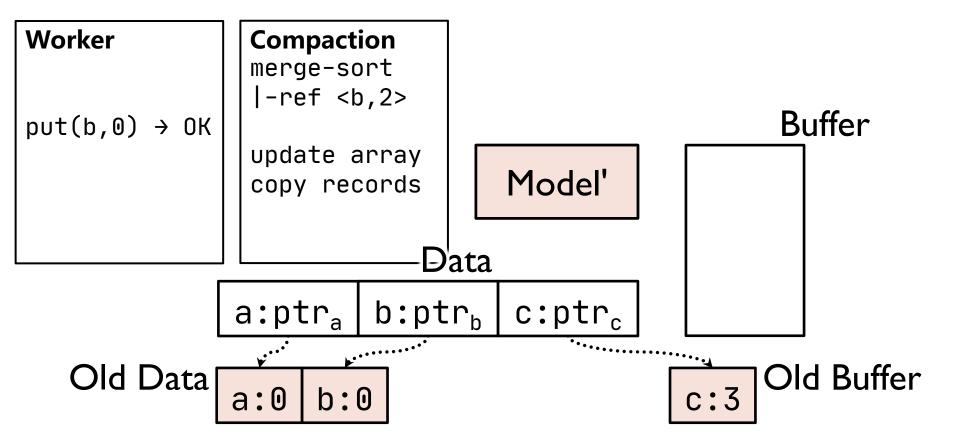
2. WAIT: use RCU* barrier to ensure no direct access to old data/buffer

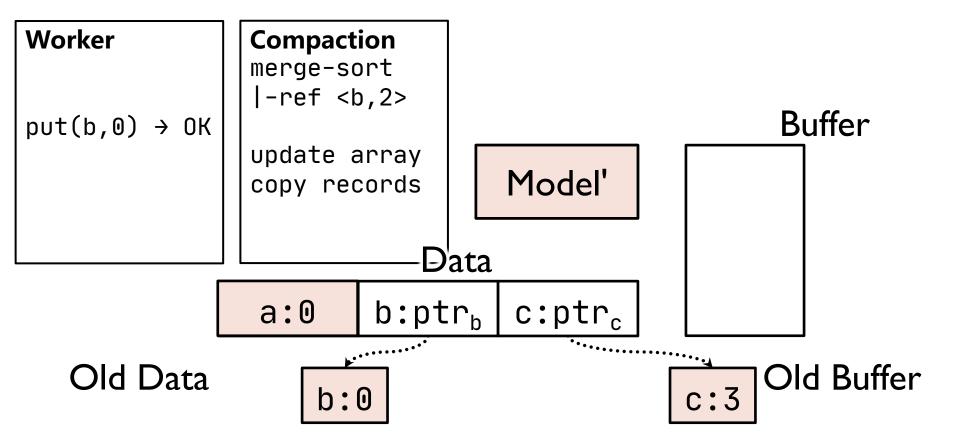


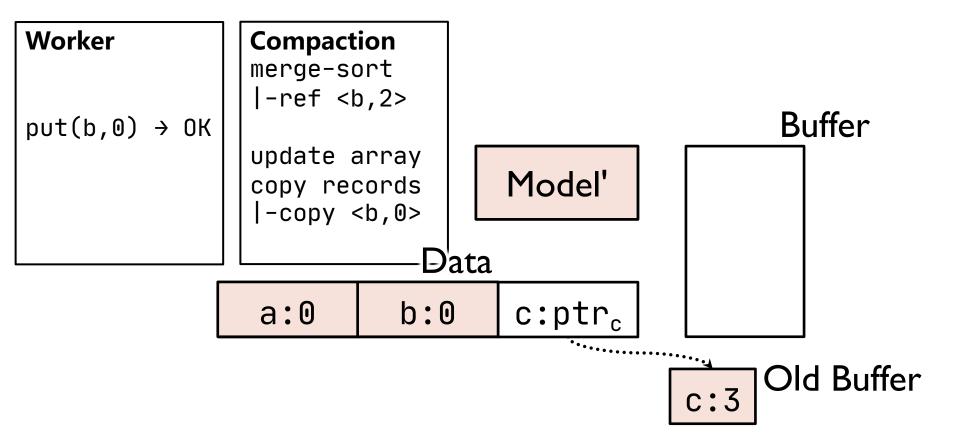
2. WAIT: use RCU* barrier to ensure no direct access to old data/buffer



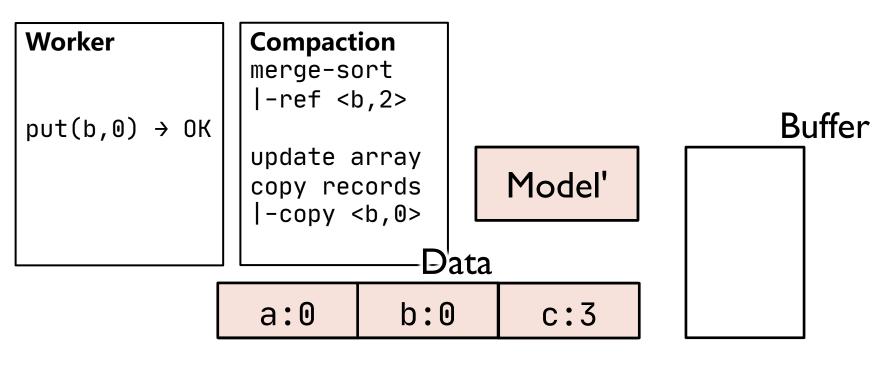
*RCU stands for Read-Copy-Update



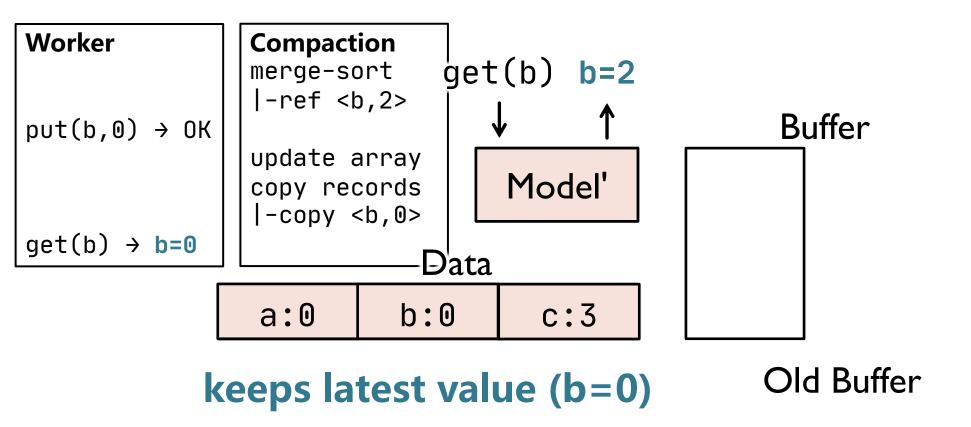


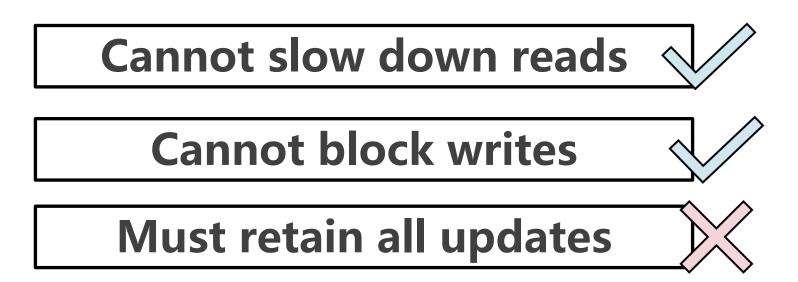


3. COPY PHASE: copy the latest records via pointers



keeps latest value (b=0)

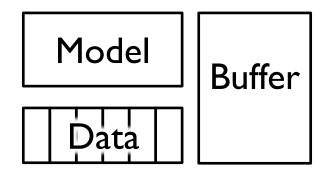


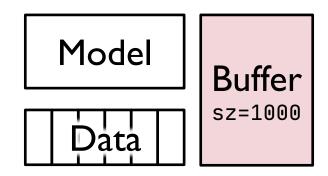


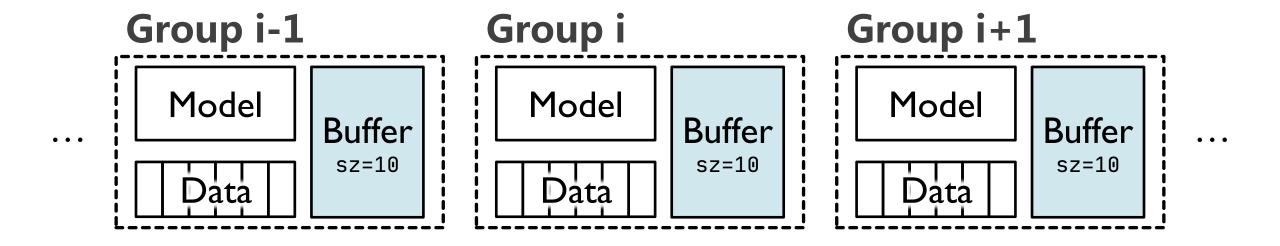
Cannot slow down reads

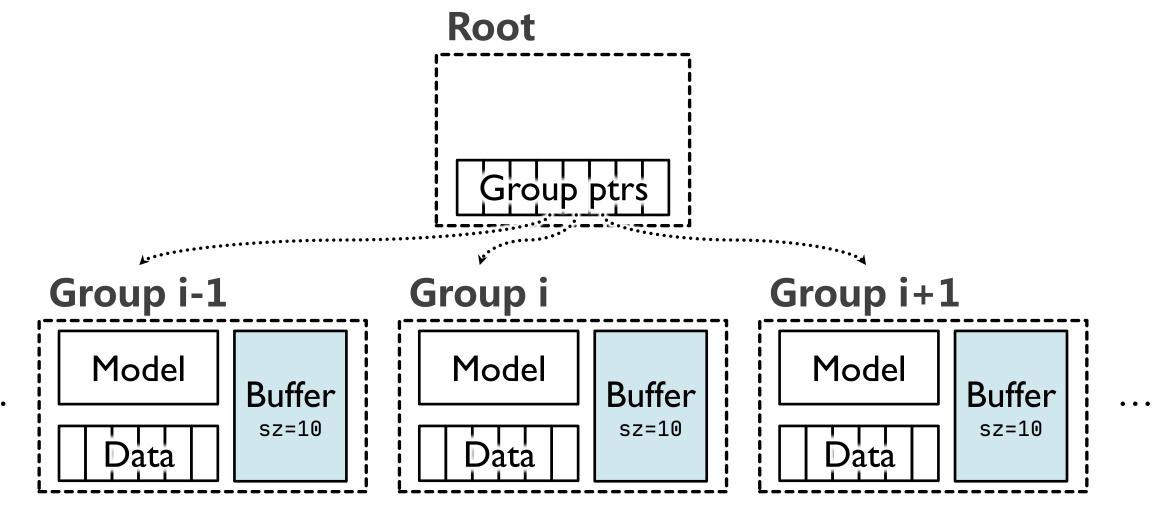
Cannot block writes

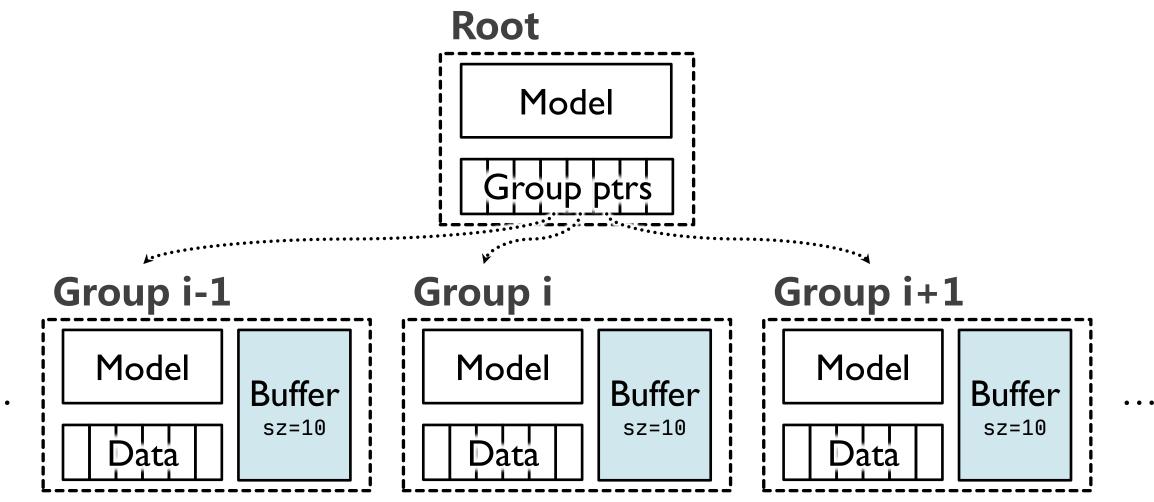
Must retain all updates











Root

Two-Phase Compaction

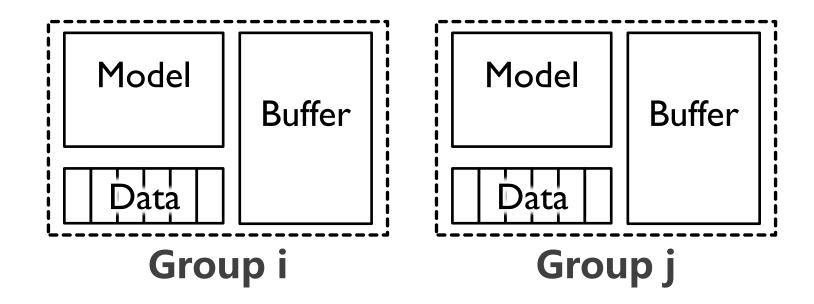
Allows efficient read and non-blocking writes

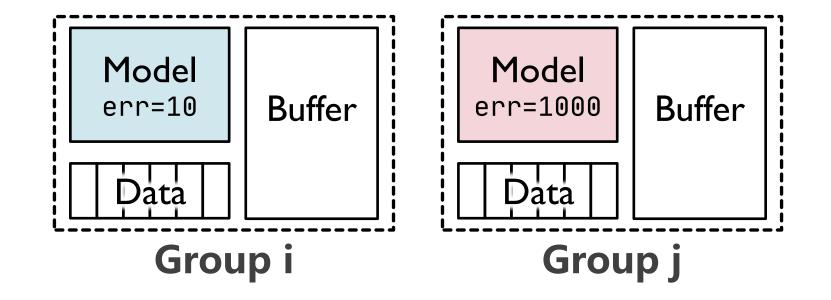
Range-partitioning

Reduces the compaction time

Fine-grained Sync. (see paper)

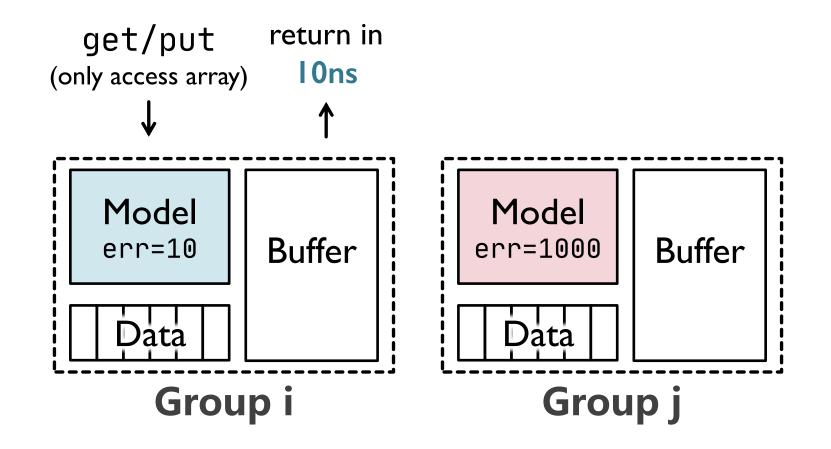
Achieves high scalability in high contention





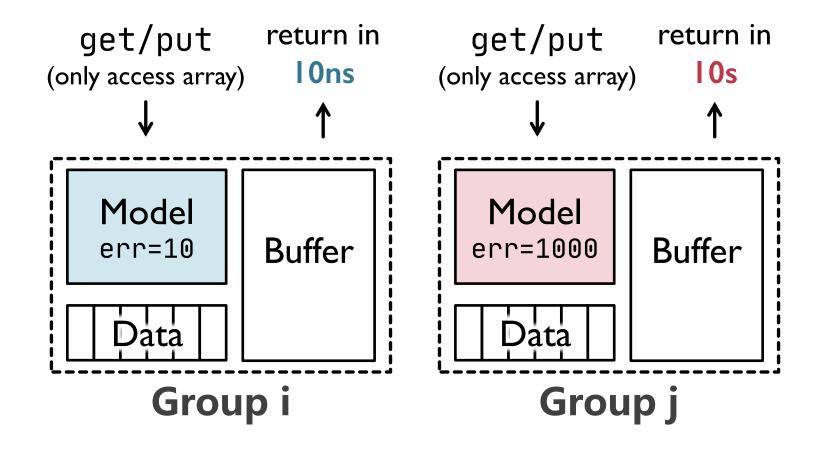






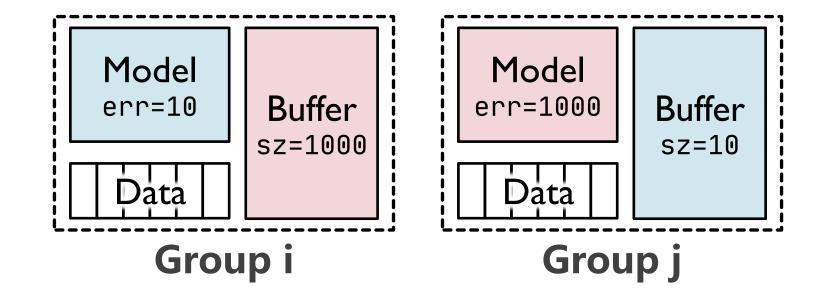






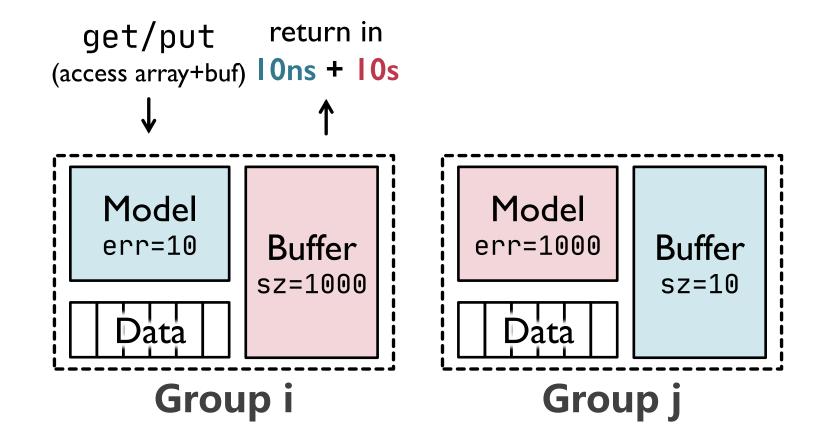






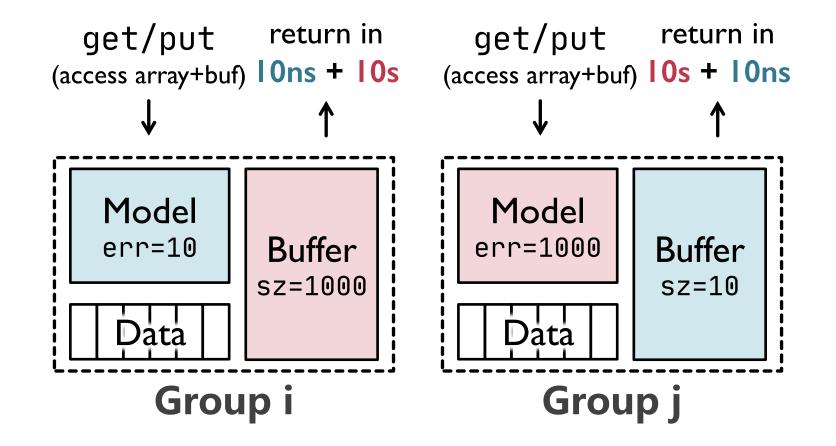










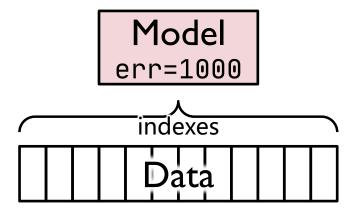




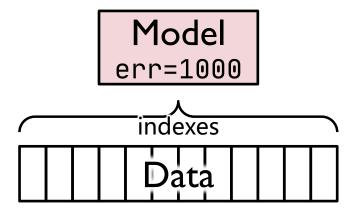


Model Split

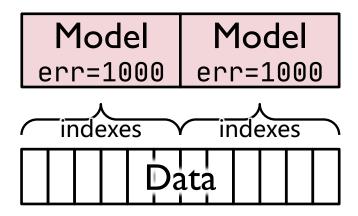
Model Split to reduce model error



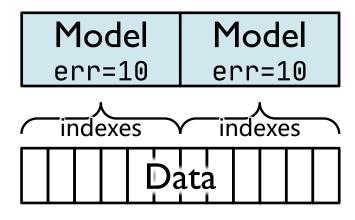
Model Split to reduce model error



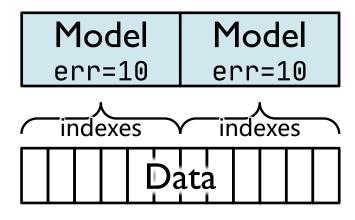
Model Split to reduce model error



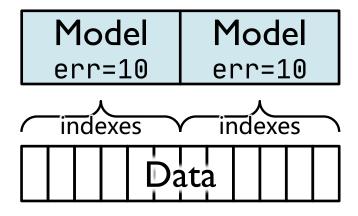
Model Split to reduce model error



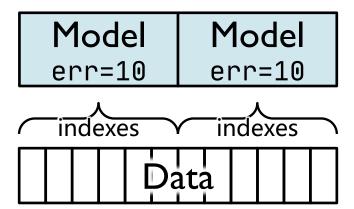
Model Split to reduce model error



Model Split to reduce model error

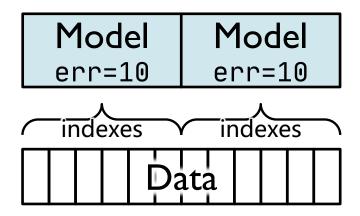


Model Merge to reduce model #

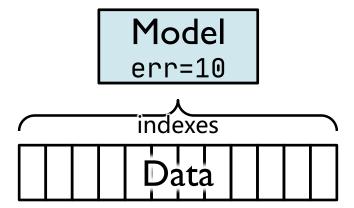


Dynamic workloads: controlling errors

Model Split to reduce model error

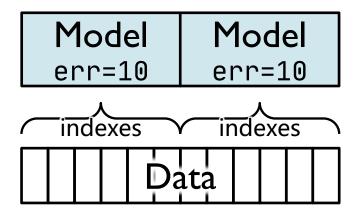


Model Merge to reduce model #

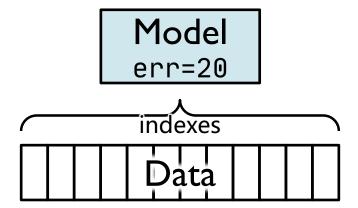


Dynamic workloads: controlling errors

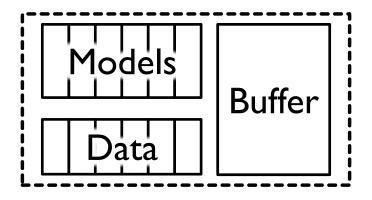
Model Split to reduce model error



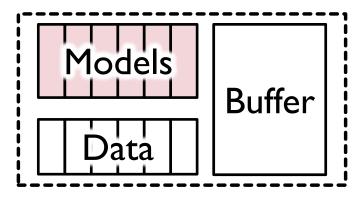
Model Merge to reduce model #



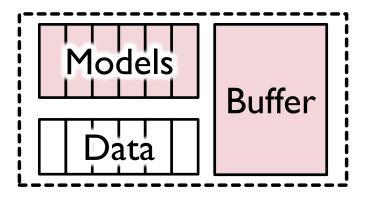
Group Split



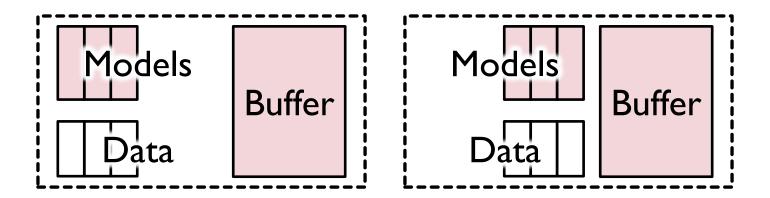
Group Split



Group Split



Group Split



Group Split

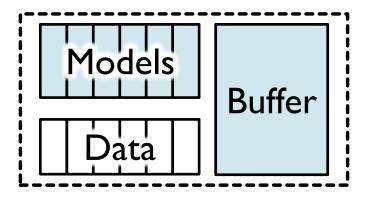


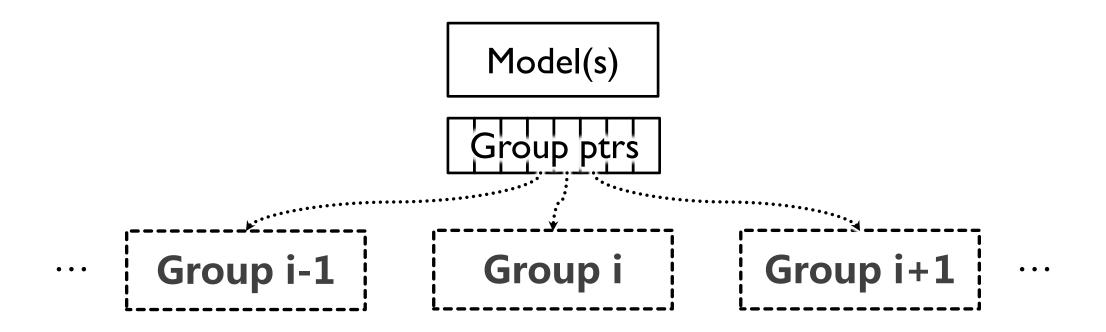
Group Merge

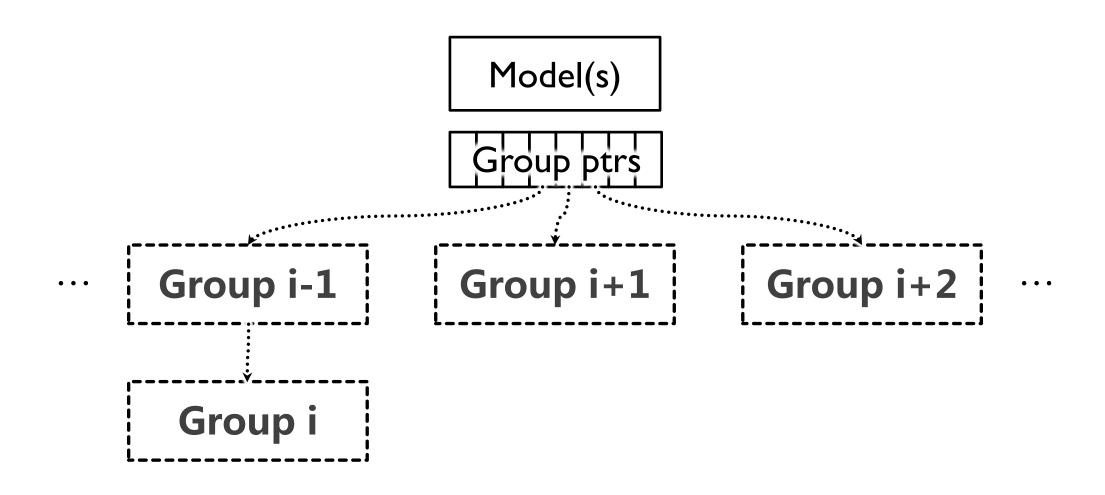
to reduce group #

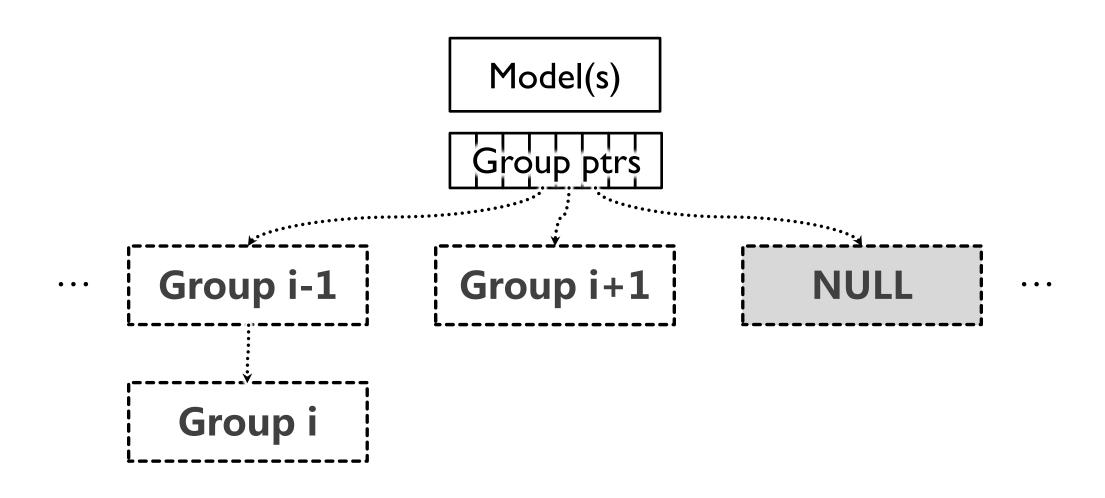


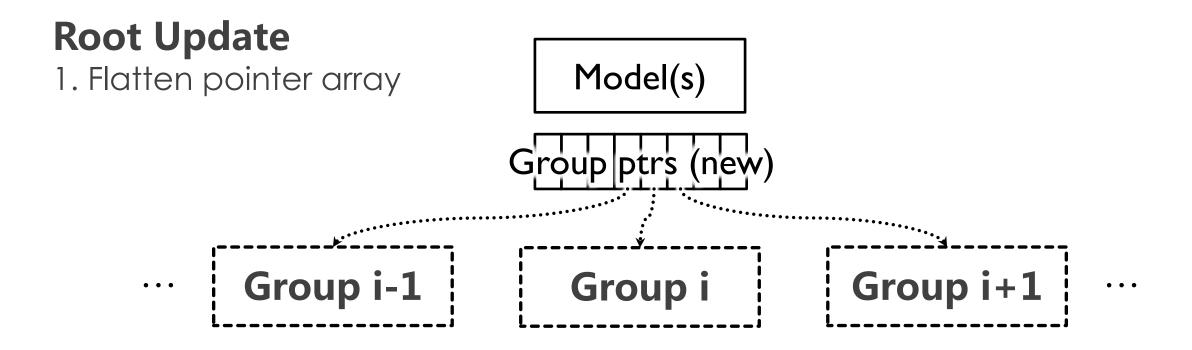
Group Merge to reduce group #

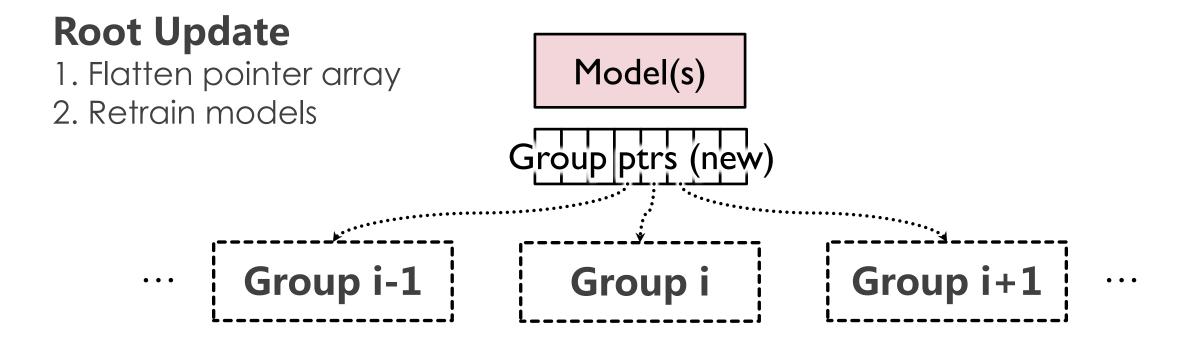


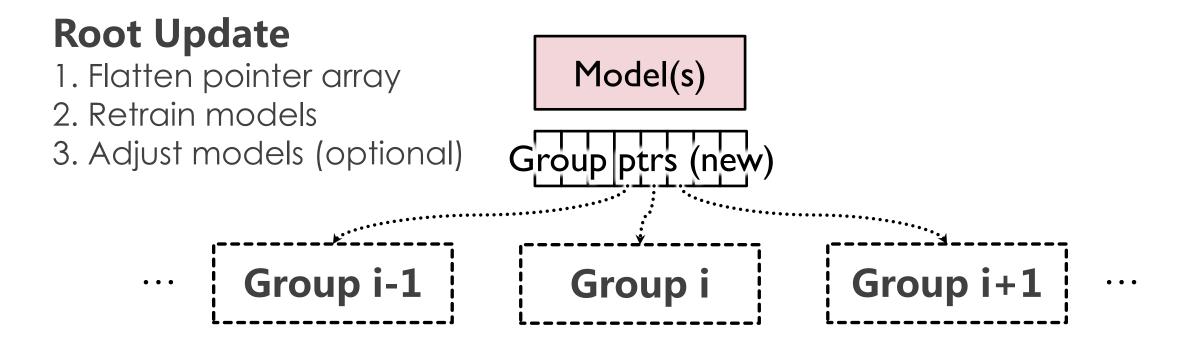












See the paper for

- Detailed pseudocode
- Fine-grained synchronization protocols
- Optimizations
- A proof sketch on linearizability
 - Formal proof in the extended version*

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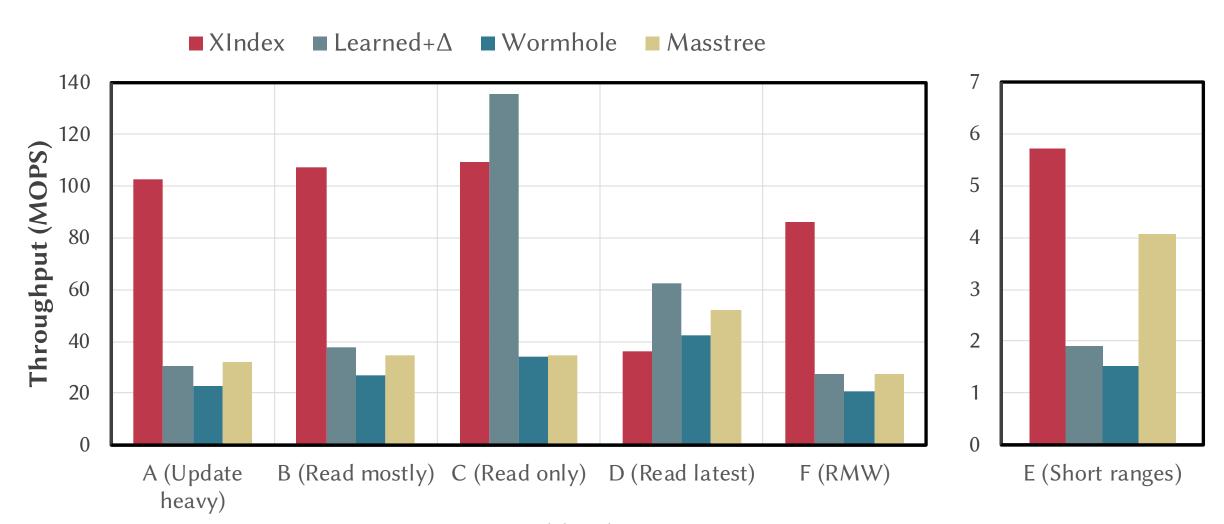
Evaluation

Evaluation Questions

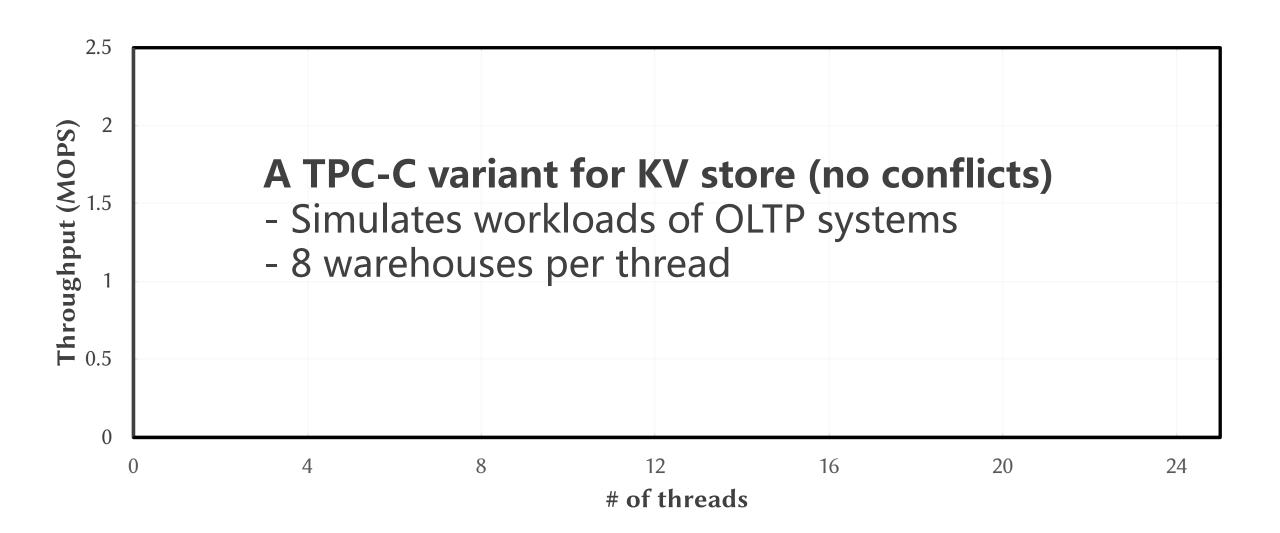
How does XIndex compare with the state-of-the-arts? Can real systems benefit from XIndex?

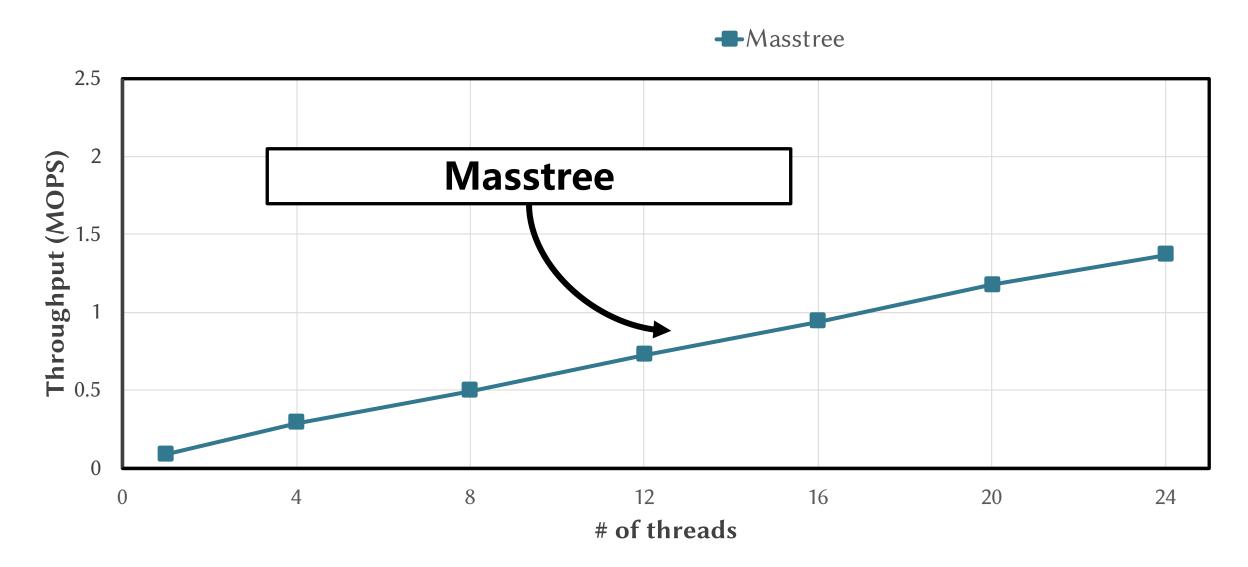
- → 2 sockets, each has 12 2.20GHz cores; 126GB Ram
- → Masstree [EuroSys '12], Wormhole [EuroSys '19], baseline learned index [SIGMOD '18]
- → 1:11 background-foreground thread ratio

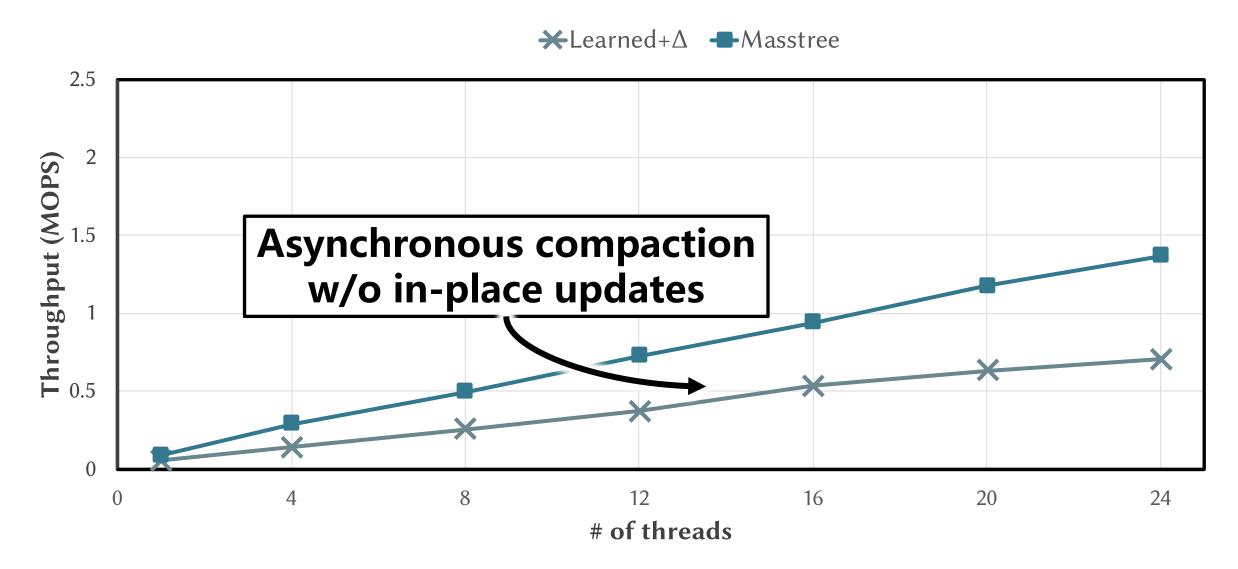
Throughput in YCSB

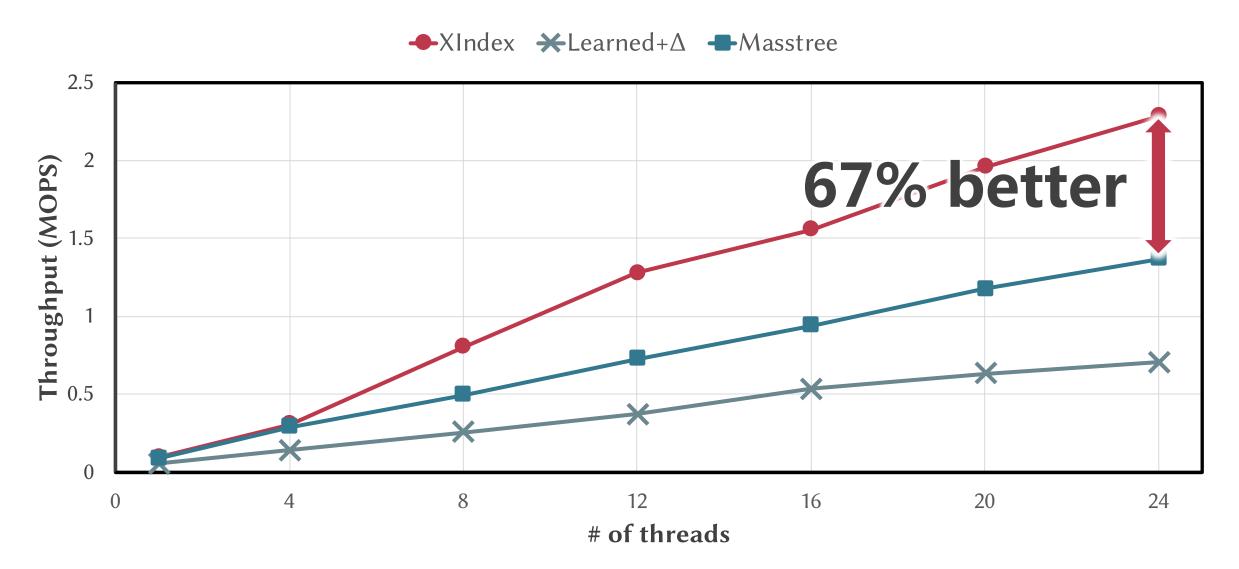


YCSB Workloads









XIndex

- ML has limitations in data structure design
- To make ML work, we need a systematics approach
 - Two-Phase Compaction for correctness and efficiency
 - FINE-GRAINED SYNCHRONIZATION for scalability
 - STRUCTURE ADJUSTMENT at runtime for stable performance



Open-sourced at

https://ipads.se.sjtu.edu.cn:1312/opensource/xindex